

MAXIMUM PRINCIPLE AND ERROR ANALYSIS

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Abstract:

The maximum principle is a fundamental concept in mathematics and engineering, providing crucial insights into the behavior of various mathematical and physical systems. This principle has wide-ranging applications in fields such as differential equations, optimal control, and numerical analysis. Error analysis, on the other hand, plays a critical role in assessing the accuracy and reliability of numerical methods and computational algorithms. This article discusses the maximum principle and its significance in error analysis, highlighting its applications and implications in various disciplines.

Keywords: maximum principle, error analysis, differential equations, numerical methods, optimal control

Introduction.

The purpose of this article is to introduce finite difference and finite element methods for solving ordinary and partial differential equations of boundary value problems.

Emphasis is placed on understanding the important details of finite difference and finite element methods and their implementation with sound mathematical theory. We begin with a comprehensive discussion of one-dimensional problems before considering two or higher dimensions. We also list some useful references for those who want to learn more about related fields. First, let's consider the concept of the maximum principle.

$$L = a \frac{\partial^2}{\partial x^2} + 2h \frac{\partial^2}{\partial x \partial y} + c \frac{\partial^2}{\partial y^2}, \quad b^2 - ac < 0, \quad \text{for } (x, y) \in \Omega,$$

we consider the elliptic differential operator and $a > 0$, $c > 0$ assume without loss of generality that The maximum principle is given in the following theorem.

Theorem 1. *If in a $u(x, y) \in C^3(\Omega)$ bounded Ω domain $Lu(x, y) \geq 0$ satisfies, then $u(x, y)$ will have a maximum value at the boundary of the field.*

Proof: If the theorem is not true, then $(x_0, y_0) \in \Omega$ has a local point, $u(x_0, y_0) \geq u(x, y)$ all $(x, y) \in \Omega$ for, a local extremum (x_0, y_0) A prerequisite for this is:

$$\frac{\partial u}{\partial x}(x_0, y_0) = 0, \quad \frac{\partial u}{\partial y}(x_0, y_0) = 0$$

Now (x_0, y_0) is not on the boundary of the domain and since $u(x, y)$ is continuous, in the domain $(x_0, y_0)_Q$ There exists a neighborhood of (x_0, y_0) , where we have a Taylor expansion (1) with superscript of

$$u(x_0 + \Delta x, y_0 + \Delta y) = u(x_0, y_0) + \frac{1}{2} \left((\Delta x)^2 u_{xx}^0 + 2\Delta x \Delta y \cdot u_{xy}^0 + (\Delta y)^2 u_{yy}^0 \right) + O\left((\Delta x)^3, (\Delta y)^3\right)$$

means that functions are evaluated. (x_0, y_0) at, that is $u_{xx}^0 = \frac{\partial^2 u}{\partial x^2}(x_0, y_0)$ in (x_0, y_0) if u is evaluated and so on.

$$u(x_0 + \Delta x, y_0 + \Delta y) \leq u(x_0, y_0) \text{ for all sufficiently small } \Delta x \text{ and } \Delta y$$

$$\frac{1}{2} \left((\Delta x)^2 u_{xx}^0 + 2\Delta x \Delta y \cdot u_{xy}^0 + (\Delta y)^2 u_{yy}^0 \right) \leq 0 \quad (1)$$

On the other hand, from the given condition

$$Lu^0 = a^0 u_{xx}^0 + 2b^0 \cdot u_{xy}^0 + c^0 u_{yy}^0 \geq 0, \quad (2)$$

Here $a^0 = a(x_0, y_0)$ and others, we rewrite the above inequality to obtain the opposition to the Taylor expansion as follows.

$$\left(\sqrt{\frac{a^0}{M}} \right) u_{xx}^0 + 2\sqrt{\frac{a^0}{M}} \frac{b^0}{\sqrt{a^0 M}} u_{xy}^0 + \left(\frac{b^0}{\sqrt{a^0 M}} \right)^2 u_{yy}^0 + \frac{u_{yy}^0}{M} \left(c^0 - \frac{(b^0)^2}{a^0} \right) \geq 0, \quad (3)$$

Here $M > 0$ is a constant. M 's position was small enough Δx and Δy is to choose.

Now if we look at the following expression,

$$\Delta x = \sqrt{\frac{a^0}{M}}, \quad \Delta y = \frac{b^0}{\sqrt{a^0 M}} \quad (4)$$

From expression (1), we know the following.

$$\frac{a^0}{M}u_{xx}^0 + \frac{2b^0}{M}u_{xy}^0 + \frac{b^0}{a^0 M}u_{yy}^0 \leq 0. \quad (5)$$

The result is the following.

$$\Delta x = 0, \quad \Delta y = \sqrt{\left(c^0 - \frac{(b^0)^2}{a^0}\right) / M}; \quad (6)$$

and again from (1),

$$(\Delta y)^2 u_{yy}^0 = \frac{1}{M} \left(c^0 - \frac{(b^0)^2}{a^0}\right) u_{yy}^0 \leq 0 \quad (7)$$

Thus, the left-hand side of (4) and (5) of (3) must not be positive, that is

$$Lu^0 = a^0 u_{xx}^0 + 2b^0 u_{xy}^0 + c^0 u_{yy}^0 \geq 0, \quad (8)$$

contradicts the condition and the proof is completed with this.

On the other hand, if $Lu < 0$, the minimum value of u is Ω_m will be within the limit. The maximum principle for general elliptic equations is as follows.

$$Lu = au_{xx} + 2bu_{xy} + cu_{yy} + d_1u_x + d_2u_y + eu = 0, \quad (x, y) \in \Omega, \\ b^2 - ac < 0, \quad a > 0, \quad c > 0, \quad e \leq 0, \quad (9)$$

be here Ω is a limited area. Then from theorem 1 $u(x, y)$ is an expression Ω of the local part cannot have a positive local maximum or a negative m local minimum.

The maximum principle and error analysis form an inseparable pair in the study of numerical methods and computational algorithms for solving differential equations and control problems. The insights provided by the maximum principle have significant implications for the accuracy, reliability, and performance of numerical techniques, guiding the development of robust and efficient computational tools for solving complex mathematical models. Understanding the principles of the maximum principle and its application in error analysis is crucial for researchers and practitioners in mathematics, engineering, and related fields, enabling them to address real-world challenges with confidence and precision.

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