

Stability, and Almost Sensitivity of Induced Maps

Amalraj. P^{1*}, P.B.Vinod Kumar²

^{1*}Research Scholar, APJ Abdul Kalam Technological University, (Department of Mathematics, Sanatana Dharma College, Alappuzha, Kerala, India) *Email address:* amalrp2929@gmail.com

²Research Supervisor, APJ Abdul Kalam Technological University, (Department of Mathematics, Rajagiri School of Engineering and Technology, Cochin, Kerala, India), *Email address:* vinodkumar.rajagiri@gmail.com

Article History:

Received: 22-07-2024

Revised: 09-09-2024

Accepted: 29-09-2024

Abstract:

Suppose that X is a compact Hausdorff space and $f : X \rightarrow X$ is continuous. We consider the space $K(X)$, the space of all compact subsets of X with Hausdorff metric H . Let $\tilde{f} : K(X) \rightarrow K(X)$ defined by $\tilde{f}(K) = f(K)$. We discuss some interconnections between the orbit of \tilde{f} and the orbit of f . By assuming the transitivity of \tilde{f} , we conclude that X contains a cantor set C with $(\text{orb}(\tilde{f}, C))^- = K(X)$. That is, orbit of a nowhere dense set is dense in the hyperspace. Along with this we introduce "almost sensitivity" and "stability" in $K(X)$. We prove that f is stable in X if and only if \tilde{f} is stable in $K(X)$. Again we prove that transitive maps are always 'almost sensitive' in $K(X)$ and hence the base map is 'almost sensitive' in X .

Keywords: Maps, continuous map, compact metric space.

1. Introduction

Normally, for studying the dynamics of the hyperspace of a compact metric space, we consider a dynamical system defined by a continuous map $f : X \rightarrow X$, describing the dynamics of points in the base space X and then we study the induced map $\tilde{f} : K(X) \rightarrow K(X)$ defined by $\tilde{f}(K) = f(K)$ for a compact set $K \subseteq X$ as a form of collective dynamics. In this context, a very natural question arises: What is the connection between dynamical properties of the base map f and the induced map \tilde{f} ?

During the past years this question has attracted many researchers.

(see[4],[5],[6],[7],[8], [9],[10] and [11]) In this paper, we prove that there exists a cantor set C in X , nowhere dense in X but its orbit is dense in $K(X)$. At the

same time we establish the fact that the set $D = \{x \in X, \overline{\text{orb}(f, x)} = X\}$, $D \neq X$ is dense in X and so it is not closed and there fore $D \neq K(X)$.

We also prove that f is 'stable' if and only if \tilde{f} is stable and \tilde{f} is 'almost sensitive' if \tilde{f} is transitive and this implies the 'almost sensitivity' of f .

Through out this paper, X denotes a Hausdorff compact metric space without isolated points with metric d and $f : X \rightarrow X$ is continuous. $K(X)$ denotes the space of all compact subsets of X with Hausdorff metric H induced by d . Let $\tilde{f} : K(X) \rightarrow K(X)$ defined by $\tilde{f}(K) = f(K)$.

2. Hyperspace and Induced Map

1. In this section we have study some properties of the induced map \tilde{f} and the base map f . By assuming the transitivity of \tilde{f} , we show that the base space X contains a cantor set C with its orbit is dense in $K(X)$. Along with this we also study the concept of 'almost sensitivity' in X and $K(X)$.

Let us use the symbol ϕ for the induced map \tilde{f} for the sake of convenience.

Definition 2.1. If $A = \{A_\mu\}_{\mu \in \mathbb{T}}$ is a collection of non-empty subsections of X , then $\text{mesh}(A) = \sup\{\text{diam}(A_\mu), \mu \in \mathbb{T}\}$.

In [2] it is proved that $(K(X), H)$ is compact.

Lemma 2.1

If $\overline{\text{orb}(\phi, K)} = X$ then for individually $A \in \text{orb}(\phi, K)$ and for all $x \in A$, $\overline{\text{orb}(f, x)} = X$

Proof.

Let $n \in \mathbb{N}$ and $x \in f^n(K)$.

We have to demonstrate that $\overline{\text{orb}(f, x)} = X$.

Take $y \in X$ and $\epsilon > 0$. Since $\overline{\text{orb}(\phi, K)} = X$ we have $\overline{\text{orb}(\phi, f^n(K))} = K(X)$

Let $\{y\} \in \text{orb}(\phi, f^n(K))$, then there exist $j \in \mathbb{N}$ such that $H(f^j(f^n(K), \{y\})) < \epsilon$.

Hence $f^j(x) \in f^j(f^n(K)) \subseteq B_\epsilon(y)$

So $B_\epsilon(y) \cap \overline{\text{orb}(f, x)} \neq \emptyset$

There fore , $\overline{\text{orb}(f, x)} = X$.

Lemma 2.2. If X is weakly mixing, then any power $X \times X \times \dots \times X$ is ergodic.

Proof. see[1]

Lemma 2.3. Let $\phi : K(X) \rightarrow K(X)$ be transitive. Then there exist a cantor set $C \subseteq X$ such that $\overline{\text{orb}(\phi, C)} = K(X)$.

Proof.

Let δ_0 represent the diameter of the set X . For every positive integer n , we define a series of finite open covers of X , denoted by $\tilde{V}_n = \{V_{n,1}, V_{n,2}, \dots, V_{n,t_n}\}$ where each $V_{n,i}$ is a nonempty subset. These covers are constructed such that the size of each cover is smaller than δ_n . In essence, this arrangement ensures that each element of the set X is contained within at least one open set in the cover, and as n increases, the covers become increasingly finer, converging towards the set's diameter.

Step 1

Let us assume W_0 and W_1 to be two non-empty disjoint open sets in X and $\text{mesh}(\{W_0 \cap W_1\}) < \delta_1$. Let $\lambda_1 = \{1, 2, \dots, t_1\} \times \{1, 2, \dots, t_1\} = \{(a, b) | a, b \in \{1, 2, \dots, t_1\}\}$.

Let us take into consideration the following $t_1^2 + 1$ collection of open sets

(W_0, W_1) and $\{(V_{1,a}, V_{1,b}) : (a, b) \in \lambda_1\}$

Then, by Lemma 1.4 [see 1], two closed subsets of X , C_0 and C_1 , having the following characteristics, exist:

- Each $\text{int}(C_i)$ is nonempty and which is contained in W_i for $i = 0, 1$.

Hence C_0 and C_1 are disjoint.

- for each $A \in \langle C_0, C_1 \rangle = \{B \in K(X) : B \subset (C_0 \cup C_1) \text{ and } B \cap C_i \neq \emptyset\}$ and for each $(a, b) \in \lambda_1$, there exist $n \in \mathbb{N}$ such that $f^n(A) \in \langle U_{1,a}, U_{1,b} \rangle$.

- Also, $f^n(A \cap C_0) \subset U_{1,a}$ and $f^n(A \cap C_1) \subset U_{1,b}$.

Let $\mathbb{C}_1 = \langle C_0, C_1 \rangle$. Then $\text{diam}(\mathbb{C}_1) < \delta_1$ for each $A \in \mathbb{C}_1$, $\text{orb}(\phi, A)$ is δ_1 -close to $F_2(X)$, where $F_2(X) = \{A \in K(X) \setminus |A| \leq 2\}$.

For, given any $\{p, q\} \in F_2(X)$, there exist $(a, b) \in \lambda_1$ such that $p \in U_{1,a}$ and $q \in U_{1,b}$.

Since there exist n so that $f^n(A) \in \langle U_{1,a}, U_{1,b} \rangle$. We conclude that $H(\{p, q\}, f^n(A)) < \delta_1$

Step 2

Let $W_{0,0}, W_{1,0}, W_{0,1}, W_{1,1}$ are 4 non-empty open subsets of X with

$$W_{0,0} \cap W_{1,0} = \emptyset \text{ and } W_{0,1} \cap W_{1,1} = \emptyset$$

$$W_{0,0} \cup W_{1,0} \subset C_0 \text{ and } W_{0,1} \cup W_{1,1} \subset C_1 \text{ and } \text{mesh}(\{W_{0,0}, W_{1,0}, W_{0,1}, W_{1,1}\}) < \delta_2.$$

Let $\lambda_2 = \{1, 2, \dots, t_2\}^4 = \{(a_1, a_2, a_3, a_4) \setminus a_i \in \{1, 2, \dots, t_2\}\}$. Consider the following $t_2^4 + 1$ collection of open sets

$$(W_{0,0}, W_{1,0}, W_{0,1}, W_{1,1}), \{(U_2, a_1, U_2, a_2, U_2, a_3, U_2, a_4)\}.$$

Given four non-empty open subsets of X , $W_{0,0}, W_{1,0}, W_{0,1}$, and $W_{1,1}$, where $W_{0,0}$ and $W_{1,0}$ are disjoint, as are $W_{0,1}$ and $W_{1,1}$. Each pair of subsets is contained within different closed sets, C_0 and C_1 , respectively. The mesh of these subsets is less than δ_2

. Then, λ_2 consists of all possible combinations of indices from 1 to t_2 . A collection of open sets is formed from the given subsets and λ_2 .

By the same result of **Lemma 1.2**[see 1] there exist 4 closed sets $C_{0,0}, C_{0,1}, C_{1,0}, C_{1,1}$ with the following properties:

1. Each $\text{int}(C_{i,j})$ is nonempty and contained in $W_{i,j}$ for $\{i, j\} \in \{0, 1\} \times \{0, 1\}$
2. For each $A \in \langle C_{0,0}, C_{0,1}, C_{1,0}, C_{1,1} \rangle$ and for each $(a_1, a_2, a_3, a_4) \in \lambda_2$ there exist $n \in \mathbb{N}$ such that $f^n(A) \in \langle U_{2,a_1}, U_{2,a_2}, U_{2,a_3}, U_{2,a_4} \rangle$, subsets of \mathbb{C}_2 namely \mathbb{C}_2^i with $f^n(A \cap \mathbb{C}_2^i) \subset U_2, a_i$ for $1 \leq i \leq 4$, where $\mathbb{C}_2 = \langle C_{0,0}, C_{0,1}, C_{1,0}, C_{1,1} \rangle$.

Note that $\text{diam}(\mathbb{C}_2) < \delta_2$ and $\mathbb{C}_2 \subset \mathbb{C}_1$ let $A \in \mathbb{C}_2$ and $\{p_1, p_2, p_3, p_4\} \in F_4(X)$, then there exist $(a_1, a_2, a_3, a_4) \in \lambda_2$ such that $p_i \in U_{2,a_i}$

Since there exist n so that $f^n(A) \in \langle U_{2,a_1}, U_{2,a_2}, U_{2,a_3}, U_{2,a_4} \rangle$.

We conclude that $H(\{p_1, a_2, a_3, a_4\}, f^n(A)) < \delta_2$.

So for every $A \in \mathbb{C}_2$, $\text{orb}(\phi, A)$ is δ_2 -close to $F_4(X)$.

Step 3

Let's say that \mathbb{C}_r has previously been defined and has the following attributes:

\mathbb{C}_r is defined as a collection of closed sets of X , represented as $\langle C_{0,0,0,\dots,0}, \dots, C_{1,1,\dots,1} \rangle$, where each closed set is indexed by a binary sequence $:\{C_{j_1 j_2 \dots j_r} \setminus (j_1, j_2, \dots, j_r) \in \{0, 1\}^r\}$. This indexing scheme corresponds to 2^r possible combinations, denoting the presence or absence of each closed set in \mathbb{C}_r . Each combination delineates the composition of \mathbb{C}_r and its constituent closed sets.

- $(j_1, j_2, \dots, j_r) \in \{0, 1\}^r$ and $\text{int}(C_{j_1 j_2 \dots j_r})$ is non empty, $C_{j_1 j_2 \dots j_r} \subset C_{j_2 \dots j_r}$ and $\text{diam}(C_{j_1 j_2 \dots j_r}) < \delta_r$
- $\text{diam}(\mathbb{C}_r)$ is less than δ_r and \mathbb{C}_r contained in \mathbb{C}_{r-1}

- For each pair $(j_1, j_2, \dots, j_r) \neq (l_1, l_2, \dots, l_r)$ in $\{0, 1\}^r$;

$C_{j_1 j_2 \dots j_r}$ and $C_{l_1 l_2 \dots l_r}$ are disjoint.

- For each $A \in \mathbb{C}_r$ and each $(t_1, t_2, \dots, t_{2^r})$ in $\lambda_r = \{t_1, t_2, \dots, t_{2^r}\}^{2^r}$ there exist $n \in \mathbb{N}$, $f^{n(A)} \in \langle U_r, t_1, U_r, t_2, \dots, U_r, t_{2^r} \rangle$, subsets of \mathbb{C}_r namely \mathbb{C}_r^i with $f^n(A \cap \mathbb{C}_r^i) \subset U_r, t_i$, for $1 \leq i \leq 2^r$.

Then for if $A \in \mathbb{C}_r$, then $orb(\phi, A)$ is δ_r close to $F_{2^r}(X)$.

Similarly, for \mathbb{C}_{r+1} .

Step 4

So we get a declining order of compact subsets of X , $\{\mathbb{C}_r\}_1^\infty$

Let $\{C_{l_1 l_2 \dots l_r} : (l_1, l_2, \dots, l_r) \in \{0, 1\}^r\}$ be the 2^r compact subset of X that define \mathbb{C}_r .

∞

Let $C = \bigcap_{r=1}^\infty (\bigcup \{C_{l_1, l_2, \dots, l_r} : (l_1, l_2, \dots, l_r) \in \{0, 1\}^r\})$.

Then C is a cantor set in X .

for all $r, C \in \mathbb{C}_r$, so $\overline{orb(\phi, C)} = K(X)$.

Theorem 2.1. *There exist a cantor set $C \subseteq X$ such that $\overline{orb(f, x)} = X$ for every $x \in f^n(C)$ for all $n \in \mathbb{N}$.*

Proof. clear from Lemma 2.3

Theorem 2.2. *Let $\tilde{f}: K(X) \rightarrow K(X)$ be transitive. Then there exist a cantor*

set $C \subseteq X$ such that $\overline{orb(f, x)} = X$ for every $x \in C$

Proof. clear from lemma 2.1 and theorem 2.2 \square

Theorem 2.3. *Let $D = \{x \in X, \overline{orb(f, x)} = X\}$ and $\tilde{f}: K(X) \rightarrow K(X)$ is transitive. Then $C \subseteq D$, that is D nonempty. Also D is a dense subset of X fully invariant under f , that is $f(D) \subseteq D$*

Proof. From theorem 2.3, we can find a cantor set C in X with $C \subseteq D$.

That is D is nonempty.

for the proof of the remaining part, see[3] and[4] \square

Theorem 2.4. *Let $\phi: K(X) \rightarrow K(X)$ is transitive and $D \neq X$. Then $D \notin K(X)$.*

Proof. from theorem 2.4, D is dense in X . So D is not closed and so it is not compact. \square

In the theorem we have a nowhere dense set C in X with its orbit $orb(\phi, C)$ is dense in $K(X)$. But at the same time we have a dense set D in X with even $D \notin K(X)$.

Theorem 2.5. *Let $\tilde{f}: K(X) \rightarrow K(X)$ is transitive and let C be the cantor set in X . Then for any $U \subseteq X$ and for any integer m , $\limsup_{n \rightarrow \infty} H(\tilde{f}^n(C), \tilde{f}^{n+m}(C)) \geq H(U, \tilde{f}^m(U))$*

Proof. Let U and m be given and let $\{\frac{1}{2^n}\}$ be the sequence.

since \tilde{f} is continuous and $\overline{orb(\tilde{f}, C)} = K(X)$ there exist for every $\frac{1}{2^n}$, a positive integer s_n such that $\tilde{f}^{s_n}(C)$ so close as to U such that $H(\tilde{f}^{s_n}(C), U) < \frac{1}{2^{n+1}}$ and $H(\tilde{f}^m(\tilde{f}^{s_n}(C)), \tilde{f}^m(U)) < \frac{1}{2^{n+1}}$.

This implies

$$H(\tilde{f}^{s_n}(C), \tilde{f}^{s_n+m}(C)) > H(U, \tilde{f}^m(U)) - \frac{1}{2^n}$$

[by using Triangle Inequality]

Hence the result.

Definition 2.3. Let X be a metric space with metric d and $f: X \rightarrow X$ be a continuous map. f is said to be almost sensitive if we can find an $x \in X$ and $m \in \mathbb{N}$ such that for any $\limsup_{n \rightarrow \infty} d(f^n(x), f^{n+m}(y)) \geq d(y, f^m(y))$.

Theorem 2.6. In $K(X)$, transitive maps are almost sensitive.

Proof. clear from Lemma 2.3 and Theorem 2.6 □

Theorem 2.7. \tilde{f} is almost sensitive in $K(X)$ implies f is almost sensitive in X

Proof. clear from Theorem 2.7

3. Stability of Induced Maps

In this section we study the stability of the induced map $\tilde{f}: K(X) \rightarrow K(X)$ and its connection with the stability of the continuous map $f: X \rightarrow X$. In this section $C(X)$ denotes the space of all continuous functions on X and $C(K(X))$ denotes the space of all continuous functions on $K(X)$.

Definition 3.1. A point $x \in X$ is said to be stable if for all $\epsilon > 0$ there is a $\delta > 0$ such that if $d(y, x) < \delta$ then $d(f^n(y), f^n(x)) < \epsilon$ for every n . A point x is said to be unstable if it is stable for f^{-1} .

Definition 3.2. $\tilde{f} \in K(X)$ is stable if given $\epsilon > 0$, there exists a $\delta > 0$ such that for each $\tilde{g} \in C(K(X))$ with $d_H(\tilde{f}, \tilde{g}) < \delta$, there exist a continuous map $h \in C(X)$ such that $\tilde{f} \circ \tilde{g} = \tilde{g} \circ \tilde{f}$ and $d_H(\tilde{h}, \tilde{i}) < \epsilon$ where $\tilde{i}: K(X) \rightarrow K(X)$ is the identity map and $d_H(\tilde{f}, \tilde{g}) = \sup \{d_H(\tilde{f}(A), \tilde{g}(A)), A \in K(X)\}$.

Theorem 3.1. $f: X \rightarrow X$ is stable in $C(X)$ if and only if $\tilde{f}: K(X) \rightarrow K(X)$ is stable in $C(K(X))$.

Proof. To prove the theorem, first we prove the following lemmas

Lemma 3.1. The map $\psi: C(X) \rightarrow C(K(X))$ given by $\psi(f) = \tilde{f}$ is an embedding of $C(X)$ into $C(K(X))$

Proof. ψ is well defined since the induced map \tilde{f} given by a continuous map is continuous.

Next we have to show that ψ is injective.

Suppose $\psi(f) = \psi(g)$.

Let $A = \{x\}$ for each $x \in X$

We have, $\{f(x)\} = \tilde{f}(A) = \tilde{g}(A) = \{g(x)\}$ for each $x \in X$.

Then, ψ is injective.

Next we have to show that ψ and ψ^{-1} are continuous.

Let $\{f_n\}$ be a sequence in sequence in $C(X)$ which converges to f . Then $\{\tilde{f}_n\}$ converges to \tilde{f} in $C(K(X))$

Assume that for any $\epsilon > 0$ and each $A \in K(X)$, there exist an $N \in \mathbb{Z}_+$ such that $d(f_n, f) < \epsilon$ for every $n \geq N$.

For all $a \in A$ and $n \geq N$, we have $d(f^n(a), f(a)) < \epsilon$

So $f^n(A) \subseteq B(f_n(A), \epsilon), n \geq N$

For all $A \in K(X)$, we get $f(A) \subseteq B(f_n(A), \epsilon)$ for every $n \geq N$

Then there exist an $N \in \mathbb{Z}_+$ such that $d(\tilde{f}_n(A), \tilde{f}(A)) < \epsilon$ for every $n \geq N$ and each $A \in K(X)$.

Similarly we show that if $\tilde{f}_n \rightarrow \tilde{f}$ in $C(K(X))$ then $f_n \rightarrow f$ in $C(X)$.

Therefore, ψ is an embedding of $C(X)$ in to $K(C(X))$.]□

Lemma 3.2. $\psi(C(X))$ is closed in $C(K(X))$

Proof. We prove that there exist a sequence $\{\tilde{f}_n\}$ in $\psi(C(X))$ which converges to F such that there is $f \in C(X)$ satisfies $\tilde{f} = F$.

Consider $\psi^{-1}(\tilde{f}_n) = f_n$.

For every $\epsilon > 0$, take $N > 0$ such that $d(\tilde{f}_n, \tilde{f}_m) < \epsilon$, for every $n, m \geq N$.

This means that any compact set A satisfies $d(\tilde{f}_n(A), \tilde{f}_m(A)) < \epsilon$ for every $n, m \geq N$.

For $A \in K(X)$, choose $A_x = \{x\}$ for every $x \in X$.

Then $d(f_n, f_m) < \epsilon$ for every $n, m \geq N$ and all $x \in X$.

Since $\{f_n\}$ is a Cauchy in $C(X)$, which is a complete metric space, there exist $f \in C(X)$ such that $\{f_n\}$ converges to f . Since ψ is continuous $\{\psi(f_n)\} = \{\tilde{f}_n\}$ Since the limit is unique, $F = \tilde{f}$

Therefore $F \in \psi(C(X))$.

Therefore $\psi(C(X))$ is closed in $C(K(X))$.

Proof of Theorem 3.1

Suppose $f: X \rightarrow X$ is stable and $\epsilon > 0$ is given. Then there are $\delta > 0$ and $h \in C(X)$ as is the definition of stability for f . Since ψ^{-1} is continuous at $\tilde{f} \in \psi(C(X))$, then for $\delta > 0$, there exist a $\delta_1 > 0$ such that if $\tilde{g} \in \psi(C(X))$ with $d(\tilde{f}, \tilde{g}) < \delta$, then we have, $d(\psi^{-1}(\tilde{f}), \psi^{-1}(\tilde{g})) = d(f, g) < \delta$.

From $f \circ h = h \circ g$, we have

$$\psi(f \circ h)(A) = (\tilde{f} \circ \tilde{g})(A)$$

$$= (f \circ h)(A)$$

$$= \tilde{f}(h(A))$$

$$= \tilde{f}(\tilde{h}(A)) = (\tilde{f} \circ \tilde{g})(A), A \in K(X)$$

$$\text{and } \psi(h \circ g)(A) = (\tilde{h} \circ \tilde{g})(A), A \in K(X)$$

$$\text{Thus } \tilde{f} \circ \tilde{h} = \tilde{h} \circ \tilde{g}.$$

Let $A \in K(X)$. From the continuity of h and compactness of A , we can see that

$$h(A) \subseteq \bigcup_{a \in A} B(a, \epsilon)$$

and

$$A \subseteq \bigcup_{a \in A} B(h(a), \epsilon)$$

if and only if

$$h(A) \subseteq B(A, \epsilon)$$

and

$$A \subseteq B(h(A), \epsilon)$$

that is, $h(A) \subseteq B(A, \epsilon)$ and $A \subseteq B(h(A), \epsilon)$ for any $A \in K(X)$.

This implies $d(\tilde{h}, \tilde{i}) < \epsilon$

Therefore, \tilde{f} is stable in $\psi(C(X))$.

Conversely, Suppose $\tilde{f} \in \psi(C(X))$ is stable.

for any $\epsilon > 0$, there exist a $\delta > 0$ and $\tilde{h} \in \psi(C(X))$ satisfying topological stability of \tilde{f} . Since ψ is continuous at $f \in C(X)$, there is a $\delta_2 > 0$ such that for any $g \in C(X)$ with $d(f, g) < \delta_2$, we have

$$d(\psi(f), \psi(g)) = d(\tilde{f}, \tilde{g}) < \delta$$

Take $A = \{x\}$ for each $x \in X$, then $\tilde{f} \circ \tilde{g} = \tilde{g} \circ \tilde{f}$ that

$$(\tilde{f} \circ \tilde{g})(A) = \{f(h(x))\}$$

$$= \{h(g(x))\}$$

$$= (\tilde{g} \circ \tilde{f})(A), x \in X$$

This implies

$$f \circ h = h \circ g.$$

From $d(\tilde{h}, \tilde{i}) < \epsilon$, we have $\tilde{f}(A) \subseteq B(A, \epsilon)$ and $A \subseteq B(\tilde{h}(A), \epsilon)$ for $A \in K(X)$.

Taking $A = \{a\}$, for each $a \in X$, implies

$$\{h(a)\} \subseteq B(a, \epsilon) \text{ and } \{a\} \subseteq B(h(a), \epsilon)$$

Since $a \in X$ is arbitrary, we obtain $d(h, i) < \epsilon$

Hence $f \in C(X)$ is stable. \square

The authors would like to express their sincere gratitude to APJ Abdul Kalam Technological University, Kerala, India; the management and Staff of Sanatana Dharma College, Alappuzha, Kerala, India and the management and Staff of Rajagiri School of Engineering and Technology, Kerala, India for their support.

References

- [1] Harry Frustenberg, *Disjointness In Ergodic Theory, Minimal Sets, and A Problem In Diophantine Approximation*, Mathematical System Theory, 1 (1967), 1-49.
- [2] Jack T. Goodykoontz, JR. and Choon Jai Rhee *Local Properties of Hyperspaces*, Topology Proceedings, 23(1998), 183–200..
- [3] Paul S. Bourdon, *Second Iterate of a Map with Dense Orbit*, Proceedings of American Mathematical Society, 124,(1996), 1577-1581.

- [4] Amalraj.P And P.B.Vinod Kumar, *nth Iterate of A map with Dense Orbit*, Topological Dynamics And Topological Data Analysis ,Springer ,(2018),177-180.
- [5] Hiroshi Hosokava, *Induced Mappings On Hyperspace*, Tsukuba J.Math , 21,1,(1997),239-250.
- [6] Amalraj.P and P.B. Vinod Kumar, *Some properties of the Cantor Set in the Hyperspace $K(X)$* , Nanotechnology Perceptions,20 No S8(2024),1267-1274.