

STUDY OF GENERALIZED α - ADMISSIBLE MODIFIED ALMOST z - CONTRACTIONS VIA SIMULATION FUNCTIONS

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Abstract. In this paper, we introduce generalized α -admissible modified almost z -contraction with the help of simulation function and obtain fixed point results in the setting of metric space and verified with an example. The presented results extend, generalize and unify several related fixed point finding in the existing literature.

1. INTRODUCTION AND PRELIMINARIES

Consider $\mathbb{N}_\neq = \mathbb{N} \cup \{0\}$, where \mathbb{N} denotes the set of positive integers. As usual \mathbb{R} indicates the set of real numbers. Furthermore, we set $R_0^+ = [0, \infty]$. Many problems in several branches of mathematics are well known to be transformed into invariant point problems in the form $Tx = x$ for self mapping T . It is worth noting that based on the work of Banach S. [7] in 1922, known as the Banach contraction principle (BCP), the metric fixed point theory took off. A lot of authors studied generalizations of this principle. In addition, Berinde [9, 10] introduced almost contractions which exhibit new features with respect to the ones of the particular results in copart as follows:

Definition 1.1. Let (X, d) be a metric space. A self mapping Γ on X is called an almost contraction if there are constants $\delta \in [0, 1)$ and $\exists L \geq 0$ such that

$$d(\Gamma x, \Gamma y) \leq \delta d(x, y) + Ld(y, \Gamma x), \forall x, y \in X. \quad (1)$$

Berinde [9, 10] investigated that every almost contraction mapping defined in a complete metric space has at least one fixed point. Subsequently, Babu et al. [6] defined the class of mapping satisfying condition (B) as follows:

Definition 1.2. Let (X, d) be a metric space. A self mapping Γ on X is said to be satisfy condition (B) if there are constants $\delta \in [0, 1)$ and $\exists L \geq 0$ such that

$$d(\Gamma x, \Gamma y) \leq \delta d(x, y) + LQd(y, \Gamma x), \forall x, y \in X. \quad (2)$$

where $Q(x, y) = \min\{d(x, \Gamma x), d(y, \Gamma y), d(x, \Gamma y), d(y, \Gamma x)\}$

They proved a fixed point theorem for such mappings in complete metric spaces. They also discussed quasi-contraction, almost contraction and the class of mapping that satisfy condition (B) in detail. Iseki et al. [20] presented definition of almost z - contraction as follows:

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Definition 1.3. Let (X, d) be a metric space and ζ . A self mapping $\Gamma : X \rightarrow X$ is called an almost z -contraction if there are constants $\theta \geq o$ such that

$$\zeta(d(\Gamma x, \Gamma y), d(x, y) + LQ(x, y), \forall x, y \in X, \quad (3)$$

where $Q(x, y)$ is defined as in Definition 1.2. Also they investigated the existence and uniqueness of a fixed point of an almost z - contraction in metric space with simulation functions.

Authos [25, 26, 27, 28] demonstrated that almost contractions type mappings have a unique fixede point in deferent metric spaces. In sequel, P. Bunpatcharacharoen et al. [11] modified almost type z - contraction mapping in metric space and obtained fixed point. Khojsteh et al. [29] Originated the notion of z - contractions by using a specific family of functions called simulation functions and proved a version of BCP. Subsequently, many researchers generalized this idea in many ways (See [30, 31, 32, 33, 34, 35, 36, 37, 38]) and proved various interesting results in the arena of fixed point theory by using simulation functions.

Definition 1.4. [29] A function $\zeta : [o, \infty)^2 \rightarrow \mathbb{R}$ is called a simulation function if ζ satisfies the following conditions:

- (ζ_1) $\zeta(o, o) = o$;
- (ζ_2) $(t, s) < s - t$ for all $t, s > o$;
- (ζ_3) if $\{t_n\}, \{s_n\}$ are sequence in (o, ∞) such that $\lim_{n \rightarrow \infty} t_n = \lim_{n \rightarrow \infty} s_n > 0$, then $\lim sup_{n \rightarrow \infty} \zeta(t_n, s_n) < 0$.

The following function $\zeta : [o, \infty) \times [o, \infty) \rightarrow \mathbb{R}$ belongs to z .

Definition 1.5. [29] A funtion $\Gamma : X \rightarrow X$ is called a z - contraction with respect to a simulation function $\zeta \in \mathcal{Z}$ on metric space (X, d) , if the following condition is satisfied

$$\zeta(d(\Gamma x, \Gamma y), d(x, y)) \leq \forall x, y \in X. \quad (4)$$

Remark 1.6. [29] It is clear from the defintion of simulation function thar $\zeta(t, s) < o$ for all $t \geq s > o$. Therefore, if Γ is a \mathcal{Z} -contraction with respect to simulation functiomn ζ , then

$$d(\Gamma x, \Gamma y) < d(x, y) \text{ for all } x, y \in X. \quad (5)$$

Theorem 1.7. [29] *Let (X, d) be a complete metric space and $\Gamma : X \rightarrow X$ be a z -contraction with respect to ζ . Then Γ has a unique fixed point $u \in X$ and for every $x_0 \in X$, the Picard sequence $\{x_n\}$ where $x_n = \Gamma x_{n-1}$ for all $n \in \mathbb{N}$ converges to this fixed point of Γ .*

It is worth mentioning that the Banch contraction is a perfect example of z -contractions by taking $(\zeta, s) = \lambda s - 1$, where $\lambda \in [0, 1)$, as the corresponding simulation function.

Argoubi et al. [4] shown that the condition (ζ_1) to be reduntant one ine above definition 1.4 of simulation functionand so redefined it as :

Definition 1.8. [4] A simulation function is a mapping $\zeta : [o, \infty)^2 \rightarrow \mathbb{R}$ satisfies the foolowing conditions:

- (i) $\zeta(t, s) < s - t$ for all $t, s > 0$;
- (ii) if $\{t_n\}$ and $\{s_n\}$ are sequences in $(0, \infty)$ such that $\lim_{n \rightarrow \infty} t_n = \lim_{n \rightarrow \infty} s_n > 0$, and $t_n < s_n$, then $\lim sup_{n \rightarrow \infty} \zeta(t_n, s_n) < 0$.

Roldan-Lopez-de Hierrow et al.[36] modified the notion of simulation function replacing (ζ_3) by (ζ'_3) of definition 1.4 as :
 (ζ'_3) if $\{t_n\}$ and $\{s_n\}$ are sequences in $(0, \infty)$ such that $\lim_{n \rightarrow \infty} t_n = \lim_{n \rightarrow \infty} s_n > 0$, and $t_n < s_n$, then $\lim sup_{n \rightarrow \infty} \zeta(t_n, s_n) < 0$.

It is clear that, if the function ζ satisfies the conditions $(\zeta_1) - (\zeta_3)$, we say that ζ is a simulation function according to the sense of Khojasteh et al [29]. If it satisfies $(\zeta_2) - (\zeta_3)$, it is a simulation function according to the sense of Argoubi et al.[4]. and if it satisfies $(\zeta), (\zeta_2)$, and (ζ'_3) , then it is a simulation function according to the sense of Roldan- Lopez- de- Hierro et al. [36].

Samet et al.[39] introduced a new category of contractive type mappings known as $\alpha-\psi$ contractive type mapping. The results obtained by Samet et al.[39] extended and generalized the existing fixed point results in the literature, in particular the Banach contraction principle. Further, Karapinar E. and Samet[16] generalized the $\alpha - \psi$ comntractive type mappings and obtained various fixed point theorems for this generalized class of contractive mappings. In 2013, Hussain et al. [17] introduced α -admissible mappings and proved fixed point theorems in metric space. Subsequently, Abdeljawad[1] introduced a pair of α -admissible mappings satisfying new sufficient contractive conditions, which are different from those in[14, 16] and obtained fixed point and common fixed point theorems. Afterward, some authors have obtained fixed point theorems for some kinds of α -admissible mappings (see [1], 2, 3, 5, 6,7, 8,12,13,14, 15,18, 20, 21,22, 24, 38,40,41 and 42).

Definition 1.9. [39] Let $\Gamma : X \rightarrow X$ and $\alpha : X \times X \rightarrow \mathbb{R}^+$ be the functions. Then Γ is called α -admissible if $\alpha(x, y) \geq 1 \Rightarrow \alpha(\Gamma x, \Gamma y) \geq 1$,

Karapinar E. [23] introduced the notion of α - admissible z - contraction and generalized the results of Samet et al.[39]and Khojasteh et al. [29]. Very recently, Dipti et al. [43] presented some fixed point results in complete metric spaces using generalized α admissible mappings embedded in the simulation functions.

Definition 1.10. [15] Let $\Gamma : X \rightarrow X$ and $\alpha : X \times X \rightarrow \mathbb{R}^+$ be a functions. Then we say that Γ is an α -orbital admissible if $\alpha(x, \Gamma x) \geq 1$ implies $\alpha(\Gamma x, \Gamma^2 x) \geq 1$. Moreover, Γ is called a triangular α - orbital admissible if Γ -orbital admissible and $\alpha(x, y) \geq 1$ and $\alpha(y, \Gamma y) \geq 1$ implies $\alpha(x, \Gamma y) \geq 1$, for all $x, y \in X$.

Definition 1.11. [23] Let $\Gamma : X \rightarrow X$ be a self map defined on a metric space (X, d) . If there exist $\zeta \in \mathbb{Z}$ and $\alpha : X \times X \rightarrow \mathbb{R}^+$ such that

$$\zeta(\alpha(x, y)d(\Gamma x, \Gamma y)d(x, y)) \geq 0, \forall x, y \in X \quad (6)$$

Then Γ is called an α -admissible z - contraction with respect to ζ .

Theorem 1.12. [23] Let (X, d) be a complete metric space and let $\Gamma : X \rightarrow X$ be an α -admissible z - contraction with respect to ζ . Suppose that

- (i) Γ is triangular α - orbital admissible;
- (ii) there exist $x_0 \in X$ such that $\alpha(x_0, \Gamma x_0) \geq 1$;
- (iii) Γ is continuous.

Then there exists $u \in X$ such that $\Gamma u = u$.

Very recently, Dipti et al. [43] presented some fixed point results in complete metric spaces using generalized α admissible mappings embedded in the simulation functions.

Definition 1.13. [43] Let (X, d) be a metric space, $\Gamma : X \rightarrow X$ be a self mapping, there exists $\zeta \in Z$ and $\alpha : X \times X \rightarrow X[0, \infty)$. Then continuous mapping Γ is called generalized α -admissible almost z - contraction with respect to ζ and $\beta \in G$ and $L \geq 0$ such that for all $x, y \in X$,

$$\zeta(\alpha(x, \Gamma x)\alpha(y, \Gamma y)d(\Gamma x, \Gamma y), K(x, y) + LQ(x, y)) \geq 0 \quad (7)$$

for all distinct $x, y \in X$, where $zeta$ is a simulation function in the sense of Definition 1.

Also

$$K(x, y) = \beta(E(x, y))E(x, y) + LN(x, y) \quad (8)$$

where

$$E(x, y) = d(x, y) + |d(x, \Gamma x) - d(y, \Gamma y)| \quad (9)$$

and

$$N(x, y) = \min\{d(x, \Gamma x), d(y, \Gamma y), d(x, \Gamma y), d(y, \Gamma x)\}. \quad (10)$$

Definition 1.14 ([11]). Let (X, d) be a metric space and ζ . We say that $\Gamma : X \rightarrow X$ is a modified almost type z -contraction if there are constants $L \geq 0$ such that

$$\zeta(d(\Gamma x, \Gamma y), K(x, y) + LQ(x, y), \forall x, y \in X, \quad (11)$$

where,

$$K(x, y) = \max \left\{ d(x, y), \frac{[1 + d(x, \Gamma x)d(y, \Gamma y)]}{1 + d(x, y)} \right\}$$

and

$$Q(x, y) = \min\{d(x, \Gamma x), d(y, \Gamma y), d(x, \Gamma y), d(y, \Gamma x)\}$$

Remark 1.15. If Γ is a modified almost type z -contraction with respect to $\zeta \in Z$, then

$$d(\Gamma x, \Gamma y) < K(x, y) + LQ(x, y) \forall x, y \in X, \quad (9)$$

Inspired and motivated by the combining the ideas in[11],[20], [25], [27] and [43], we introduce a new class of mappings, and define generalized α -admissible modified almost z contraction with respect to ζ in the setting of metric space and obtain the existence and uniqueness of fixed point of such map.

2. MAIN RESULTS

Finally, we give the following definition which will be used in our main results.

Definition 2.1. Let (X, d) be a metric space, $\Gamma : X \rightarrow X$ be a self mapping, there exists $\zeta \in Z$ and $\alpha : X \times X \rightarrow X[0, \infty)$. Then continuous mapping Γ is called generalized α -admissible modified almost z - contraction with respect to ζ and $L \geq 0$ such that for all $x, y \in X$,

$$\zeta(\alpha(x, \Gamma x)\alpha(y, \Gamma y)d(\Gamma x, \Gamma y), K(x, y) + LQ(x, y)) \geq 0 \quad (10)$$

where ζ is a simulation function in the sense of Definition 1.4.

Also

$$K(x, y) = \max \left\{ d(x, y), \frac{[1 + d(x, \Gamma x)]d(y, \Gamma y)}{1 + d(x, y)}, \frac{[1 + d(x, \Gamma y)]d(y, \Gamma x)}{1 + d(x, y)} \right\} \quad (11)$$

and

$$Q(x, y) = \min \left\{ d(x, \Gamma x), d(y, \Gamma y), d(x, \Gamma y), d(y, \Gamma x), \frac{d(x, \Gamma y)d(y, \Gamma x)}{1 + d(x, y)}, \frac{d(x, \Gamma x)d(y, \Gamma y)}{1 + d(x, y)} \right\}. \quad (12)$$

We can now state the main finding of this paper.

Theorem 2.2. Let (X, d) be a complete metric space and $\Gamma : X \rightarrow X$ is a generalized α -admissible modified almost z - contraction with respect to ζ . Furthermore, we suppose for all $x, y \in X$ such that:

- (i) Γ is triangular α - orbital admissible;
- (ii) there exists $x_0 \in X$ such that $\alpha(x_0, \Gamma x_0) \geq 1$;
- (iii) Γ is continuous.
- (iv) $\alpha(x, \Gamma x) \geq 1$

Then Γ has a unique fixed point $x^* \in X$.

Proof. By (ii), there exists $x_0 \in X$ such that $\alpha(x_0, \Gamma x_0) \geq 1$, and let $\{x_n\}$ be the iterative sequence X defined by

$$x_{n+1} = \Gamma x_n, \text{ for all } n \in \mathbb{N} \quad (13)$$

If there exists some nonnegative integer n such that $x_n = x_{n+1} = \Gamma x_n$, then x_n is a fixed point of Γ . Therefore, to continue our proof, we assume that $x_n \neq x_{n+1}$ for all $n \in \mathbb{N}$. Since Γ is an α - admissible mapping, we have

$$\alpha(x_0, x_1) = \alpha(x_0, \Gamma x_0) \Rightarrow \alpha(\Gamma x_0, \Gamma x_1) = \alpha(x_1, x_2) \geq 1. \quad (14)$$

By induction, we get

$$\alpha(x_n, x_{n+1}) \geq 1, \text{ for all } n \in \mathbb{N} \cup \{0\}. \quad (15)$$

Applying the condition (10), putting $x = x_{n-1}$ and $y = x_n$ and by using (15), we have

$$\begin{aligned} 0 &\leq \zeta(\alpha(x_{n-1}, \Gamma x_{n-1}), \alpha(x_n, \Gamma x_n), d(\Gamma x_{n-1}, \Gamma x_n), K(x_{n-1}, x_n) + LQ(x_{n-1}, x_n)) \\ &= \zeta(\alpha(x_{n-1}, x_n), \alpha(x_n, x_{n+1}), d(x_n, x_{n+1})K(x_{n-1}, x_n) + LQ(x_{n-1}, x_n) \\ &< K(x_{n-1}, x_n) + LQ(x_{n-1}, x_n) - \alpha(x_{n-1}, x_n), \alpha(x_n, x_{n+1}), d(x_n, x_{n+1})) \end{aligned} \quad (16)$$

Also, where

$$\begin{aligned}
 K(x_{n-1}, x_n) &= \max \left\{ d(x_{n-1}, x_n), \frac{[1 + d(x_{n-1}, \Gamma x_{n-1})]d(x_n, \Gamma x_n)}{1 + d(x, y)}, \frac{[1 + d(x_{n-1}, \Gamma x_n)]d(x_n, \Gamma x_{n-1})}{1 + d(x, y)} \right\} \\
 &\leq \max \left\{ d(x_{n-1}, x_n), \frac{[1 + d(x_{n-1}, x_n)]d(x_n, x_{n+1})}{1 + d(x_{n-1}, x_n)}, \frac{[1 + d(x_{n-1}, x_{n+1})]d(x_n, x_n)}{1 + d(x_{n-1}, x_n)} \right\} \\
 &= \max \{d(x_{n-1}, x_n), d(x_n, x_{n+1})\} \tag{17}
 \end{aligned}$$

and

$$\begin{aligned}
 Q(x_{n-1}, x_n) &= \min \{d(x_{n-1}, \Gamma x_{n-1}), d(x_n, \Gamma x_n), d(x_{n-1}, \Gamma x_n), d(x_n, \Gamma x_{n-1}), \\
 &\quad \frac{d(x_{n-1}, \Gamma x_n)d(x_n, \Gamma x_{n-1})}{1 + d(x_{n-1}, x_n)}, \frac{d(x_{n-1}, \Gamma x_{n-1})d(x_n, \Gamma x_n)}{1 + d(x_{n-1}, x_n)}\} \\
 &\leq \min \{d(x_{n-1}, x_n), d(x_n, x_{n+1}), d(x_{n-1}, x_{n+1}), d(x_n, x_n), \frac{d(x_{n-1}, x_{n+1})d(x_n, x_n)}{1 + d(x_{n-1}, x_n)}, \\
 &\quad \frac{d(x_{n-1}, x_n)d(x_n, x_{n+1})}{1 + d(x_{n-1}, x_n)}\} \\
 &\leq \min \left\{ d(x_{n-1}, x_n), d(x_n, x_{n+1}), d(x_{n-1}, x_{n+1}), 0, 0, \frac{d(x_{n-1}, x_n)d(x_n, x_{n+1})}{1 + d(x_{n-1}, x_n)} \right\} \\
 &= 0. \tag{18}
 \end{aligned}$$

By (16), and taking in account (15),(17) ,and(18), we derive that

$$0 < \max \{d(x_{n-1}, x_n), d(x_n, x_{n+1})\} - \alpha(x_{n+1}, x_n), \alpha(x_n, x_{n+1})d(x_n, x_{n+1}) \tag{19}$$

which implies that

$$\begin{aligned}
 d(x_n, x_{n+1}) &\leq \alpha(x_{n-1}, x_n), \alpha(x_n, x_{n+1})d(x_n, x_{n+1}) \\
 &< \max \{d(x_{n-1}, x_n), d(x_n, x_{n+1})\} \quad \forall n \geq 1. \tag{20}
 \end{aligned}$$

If $\max \{d(x_{n-1}, x_n), d(x_n, x_{n+1})\} = d(x_n, x_{n+1})$ for some $n \geq 1$, then from (20), we get

$$d(x_n, x_{n+1}) \leq \alpha(x_{n-1}, x_n), \alpha(x_n, x_{n+1})d(x_n, x_{n+1}) < d(x_n, x_{n+1}). \tag{21}$$

which is contradiction, therefore,

$$\max \{d(x_{n-1}, x_n), d(x_n, x_{n+1})\} = d(x_{n-1}, x_n) \tag{22}$$

Hence

$$\begin{aligned}
 d(x_n, x_{n+1}) &\leq \alpha(x_{n-1}, x_n), \alpha(x_n, x_{n+1}), d(x_n, x_{n+1}) \\
 &< d(x_{n-1}, x_n). \tag{23}
 \end{aligned}$$

Consequently, we deduce that $\{d(x_{n-1}, x_n)\}$ is a monotonically decreasing sequence for nonnegative reals and bounded below by zero. so, there exists $r \geq 0$ such that

$$\lim_{n \rightarrow \infty} d(x_{n-1}, x_n) = r \tag{24}$$

we claim that

$$\lim_{n \rightarrow \infty} d(x_{n-1}, x_n) = 0. \quad (25)$$

$$(26)$$

On the contrary, assume that $r > 0$ and using equation(23) we have the following

$$\lim_{n \rightarrow \infty} \alpha(x_{n-1}, x_n), \alpha(x_n, x_{n+1}), d(x_n, x_{n+1}) = r \quad (27)$$

Now, we take

$$t_n = \{\alpha(x_{n-1}, x_n), \alpha(x_n, x_{n+1}), d(x_n, x_{n+1}) \text{ and } s_n = \{d(x_{n-1}, x_n)\}.$$

then

$$\lim_{n \rightarrow \infty} t_n = \lim_{n \rightarrow \infty} s_n = r \quad (28)$$

Since T is a generalized α - admissible modified almost z - contraction with respect to $\zeta \in Z$. Therefore, by (ζ_3) and equation (21) and taking limit as $n \rightarrow \infty$, we have $\limsup_{n \rightarrow \infty} \zeta(t_n, s_n) < 0$ i.e.

$$0 \leq \limsup_{n \rightarrow \infty} \zeta(\alpha(x_{n-1}, x_n), \alpha(x_n, x_{n+1}), d(x_n, x_{n+1}), d(x_{n-1}, x_n)) < 0 \quad (29)$$

This is a contradiction. Then we deduce that $r = 0$, that is, we have following

$$\lim_{n \rightarrow \infty} d(x_{n-1}, x_n) = 0 \quad (30)$$

Now, we will show that sequence $\{x_n\}$ is aCauchy sequence in X . Assume that $\{x_n\}$ is not a Cauchy sequence, then there exists $\epsilon > 0$ and two sequences $\{n_k\}$, $\{m_k\}$: $m_k > n_k > k$ such that

$$d(x_{m_k}, x_{n_k}) \leq \epsilon. \quad (31)$$

and

$$d(x_{m_k}, x_{n_k-1}) \leq \epsilon, \text{ for all } m, n, k \in \mathbb{N} \quad (32)$$

By applying the triangel inequality and using equations (30) and (31), we get the following

$$\begin{aligned} \epsilon &< d(x_{m_k}, x_{n_k}) \\ &\leq d(x_{m_k}, x_{n_k-1}) + d(x_{n_k-1}, x_{n_k}) \\ &\leq d(x_{n_k-1}, x_{n_k}) + \epsilon \end{aligned} \quad (33)$$

Taking $k \rightarrow \infty$ in equation (33) and using equation(30), we get

$$\lim_{n \rightarrow \infty} d(x_{m_k}, x_{n_k}) = \epsilon. \quad (34)$$

Again, using the triangel inequality, we have

$$\begin{aligned} d(x_{m_k}, x_{n_k}) &\leq d(x_{m_k}, x_{n_k-1}) + d(x_{n_k-1}, x_{n_k}) \\ &\leq d(x_{m_k}, x_{n_k-1}) + d(x_{m_k-1}, x_{n_k-1}) + d(x_{n_k-1}, x_{n_k}) \end{aligned} \quad (35)$$

Again, we have

$$d(x_{m_k-1}, x_{n_k-1}) \leq d(x_{m_k-1}, x_{m_k}) + d(x_{m_k}, x_{n_k-1}) + d(x_{m_k-1}, x_{m_k}) \quad (36)$$

By taking the limit as $k \rightarrow \infty$ in equation (35), (36), and using (30) we deduce that

$$\lim_{n \rightarrow \infty} d(x_{m_k-1}, x_{n_k-1}) < \epsilon. \quad (37)$$

By the same reasoning as above, we get that

$$\lim_{n \rightarrow \infty} d(x_{m_k}, x_{n_k-1}) = \lim_{n \rightarrow \infty} d(x_{m_k-1}, x_{n_k}) = \epsilon. \quad (38)$$

Since T is triangular α -orbital admissible, we have

$$\alpha d(x_{m_k-1}, x_{n_k-1}) \leq 1. \quad (39)$$

Moreover, since T is a generalized α -admissible modified almost z -contraction with respect to ζ ,

$$\begin{aligned} 0 &\leq \zeta(\alpha(x_{m_k-1}, \Gamma x_{m_k-1}), \alpha(x_{n_k-1}, \Gamma x_{n_k-1}), d(\Gamma x_{m_k-1}, \Gamma x_{n_k-1})K(x_{m_k-1}, x_{n_k-1}) + LQ(x_{m_k-1}, x_{n_k-1})) \\ &= \zeta(\alpha(x_{m_k-1}, x_{m_k}), \alpha(x_{n_k-1}, x_{n_k}), d(x_{m_k}, x_{n_k}), K(x_{m_k-1}, x_{n_k-1}) + LQ(x_{m_k-1}, x_{n_k-1})) \end{aligned}$$

It follows from condition (ζ_2) , we get

$$0 < K(x_{m_k-1}, x_{n_k-1}) + LQ(x_{m_k-1}, x_{n_k-1}) - \zeta(\alpha(x_{m_k-1}, x_{m_k}), \alpha(x_{n_k-1}, x_{n_k}), d(x_{m_k}, x_{n_k})) \quad (40)$$

Hence,

$$\begin{aligned} 0 < d(x_{m_k}, x_{n_k}) &\leq \alpha(x_{m_k-1}, x_{m_k}), \alpha(x_{n_k-1}, x_{n_k})d(x_{m_k}, x_{n_k}) \\ &< K(x_{m_k-1}, x_{n_k-1}) + LQ(x_{m_k-1}, x_{n_k-1}) \end{aligned} \quad (41)$$

Also, where

$$\begin{aligned} K(x_{m_k-1}, x_{n_k-1}) &= \max\{d(x_{m_k-1}, x_{n_k-1}), \frac{[1 + d(x_{m_k-1}, \Gamma x_{m_k-1})]d(x_{n_k-1}, \Gamma x_{n_k-1})}{1 + d(x_{m_k-1}, x_{n_k-1})} \\ &\quad \frac{[1 + d(x_{m_k-1}, \Gamma x_{n_k-1})]d(x_{n_k-1}, \Gamma x_{m_k-1})}{1 + d(x_{m_k-1}, x_{n_k-1})}\} \\ &= \max\{d(x_{m_k-1}, x_{n_k-1}), \frac{[1 + d(x_{m_k-1}, x_{m_k})]d(x_{n_k-1}, x_{n_k})}{1 + d(x_{m_k-1}, x_{n_k-1})} \\ &\quad \frac{[1 + d(x_{m_k-1}, x_{n_k})]d(x_{n_k-1}, x_{m_k})}{1 + d(x_{m_k-1}, x_{n_k-1})}\}. \end{aligned} \quad (42)$$

and,

$$\begin{aligned} Q(x_{m_k-1}, x_{n_k-1}) &= \min\{d(x_{m_k-1}, \Gamma x_{m_k-1}), d(x_{n_k-1}, \Gamma x_{n_k-1}), d(x_{m_k-1}, \Gamma x_{n_k-1}), d(x_{n_k-1}, \Gamma x_{m_k-1}), \\ &\quad \frac{d(x_{m_k-1}, \Gamma x_{n_k-1})d(x_{m_k-1}, \Gamma x_{m_k-1})}{1 + d(x_{m_k-1}, x_{n_k-1})}, \frac{d(x_{m_k-1}, \Gamma x_{m_k-1})d(x_{n_k-1}, \Gamma x_{n_k-1})}{1 + d(x_{m_k-1}, x_{n_k-1})}\} \\ &= \min\{d(x_{m_k-1}, x_{m_k}), d(x_{n_k-1}, x_{n_k}), d(x_{m_k-1}, x_{n_k}), d(x_{n_k-1}, x_{m_k}), \\ &\quad \frac{d(x_{m_k-1}, x_{n_k})d(x_{m_k-1}, x_{m_k})}{1 + d(x_{m_k-1}, x_{n_k-1})}, \frac{d(x_{m_k-1}, x_{m_k})d(x_{n_k-1}, x_{n_k})}{1 + d(x_{m_k-1}, x_{n_k-1})}\} \end{aligned} \quad (43)$$

Taking limit as $k \rightarrow \infty$ in (42), (43) using (30), (34), (37) and (38), we get

$$\lim_{k \rightarrow \infty} K(x_{m_k-1}, x_{n_k-1}) = \epsilon. \quad (44)$$

and,

$$\lim_{k \rightarrow \infty} Q(x_{m_k-1}, x_{n_k-1}) = 0. \quad (45)$$

From (34), (37), (40), and (44) (45), also condition (ζ_3) , we get

$$0 \leq \limsup_{k \rightarrow \infty} \zeta(\alpha(x_{m_k-1}, x_{m_k}), \alpha(x_{n_k-1}, x_{n_k}), d(x_{m_k}, x_{n_k})K(x_{m_k-1}, x_{n_k-1}) + LQ(x_{m_k-1}, x_{n_k-1})) \\ \leq \limsup_{k \rightarrow \infty} \zeta(\alpha(x_{m_k-1}, x_{m_k}), \alpha(x_{n_k-1}, x_{n_k}), d(x_{m_k}, x_{n_k})K(x_{m_k-1}, x_{n_k-1})) < 0.$$

This is a contradiction. Hence $\{x_n\}$ is a Cauchy sequence. Since (X, d) is complete metric space, there exists $x^* \in X$ such that

$$\lim_{n \rightarrow \infty} d(x_n, x^*) = 0. \quad (46)$$

Now, we shall show that $\Gamma x^* = x^*$. Since Γ is continuous, we obtain that

$$\begin{aligned} \Gamma x^* &= \Gamma(\lim_{n \rightarrow \infty} x_n) \\ &= \lim_{n \rightarrow \infty} \Gamma(x_n) \\ &= \lim_{n \rightarrow \infty} x_{n+1} \\ &= x^*. \end{aligned}$$

Thus, x^* is a fixed point of Γ . To prove the uniqueness of the fixed point. Assume that, x^* and y^* be two fixed point of Γ and hence $x^*, y^* \in \text{Fix}(\Gamma)$, which is a generalized α -admissible modified self mapping of metric space (X, d) . Then $d(x^*, y^*) > 0$. By (10), we have that

$$0 \leq \zeta(\alpha(x^*, \Gamma x^*), \alpha(y^*, \Gamma y^*)d(\Gamma x^*, \Gamma y^*), K(x^*, y^*) + LQ(x^*, y^*)) \quad (47)$$

where $K(x^*, y^*) = d(x^*, y^*)$ and $Q(x^*, y^*) = 0$. Then, by (47), we get

$$\begin{aligned} 0 &\leq \zeta(\alpha(x^*, x^*), \alpha(y^*, y^*), d(x^*, y^*)K(x^*, y^*) + LQ(x^*, y^*)) \\ &< K(x^*, y^*) + LQ(x^*, y^*) - \alpha(x^*, x^*), \alpha(y^*, y^*), d(x^*, y^*) \\ 0 &< d(x^*, y^*) - d(x^*, y^*) \\ &= 0. \end{aligned} \quad (48)$$

which is a contradiction. Thus we have $x^* = y^*$. Hence Γ has a unique fixed point. \square

Theorem 2.3. Let (X, d) be a complete metric space and $\Gamma : X \rightarrow X$ is a generalized α -admissible modified almost z - contraction with respect to ζ satisfying the following conditions:

- (i) Γ is triangular α - orbital admissible;
- (ii) there exists $x_0 \in X$ such that $\alpha(x_0, \Gamma x_0) \geq 1$;
- (iii) if $\{x_n\}$ is a sequence in X such that $\alpha(x_n, x_{n+1}) \leq 1$ for all $n \in \mathbb{N} \cup \{0\}$ and $x_n \rightarrow x \in X$ as $n \rightarrow \infty$, then there exists a subsequence $\{x_{n(k)}\}$ of $\{x_n\}$ such that $\alpha(x_{n(k)}, x^*) \leq 1$;
- (iv) $\alpha(x, y) \geq 1$, for all $x, y \in \text{Fix}(\Gamma)$, where $\text{Fix}(\Gamma)$ denotes the set of fixed point of Γ . Then, Γ has a unique fixed point $x^* \in X$.

Proof. By (ii), suppose $x_0 \in X$ such that $\alpha(x_0, \Gamma x_0) \geq 1$. there exists $x_n \in X$ such that $x_{n+1} = \Gamma x_n$, for all $n \in \mathbb{N}$. We have by Theorem 2.2, $\{x_n\}$ is a Cauchy sequence such that $\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = 0$. Since (X, d) is complete, there exists $x^* \in X$ such that $x_n \rightarrow x^*$. By (15) and the condition (iii), there exists a subsequence $\{x_{n(k)}\}$ of $\{x_n\}$ such that $\alpha(x_{n(k)}, x^*) \leq 1$ for all $k \in \mathbb{N}$. Using (10),

we have

$$\begin{aligned}
 0 &\leq \zeta(\alpha(x_{n_k}, \Gamma x_{n_k}), \alpha(x^*, \Gamma x^*), d(\Gamma x_{n_k}, \Gamma x^*)K(x_{n_k}, x^*) + LQ(x_{n_k}, x^*)) \\
 &= \zeta(\alpha(x_{n_k}, x_{n_k+1}), \alpha(x^*, \Gamma x^*)d(x_{n_k+1}, \Gamma x^*), K(x_{n_k}, x^*) + LQ(x_{n_k}, x^*)) \\
 &< K(x_{n_k}, x^*) + LQ(x_{n_k}, x^*) - \alpha(x_{n_k}, x_{n_k+1}), \alpha(x^*, \Gamma x^*), d(x_{n_k+1}, \Gamma x^*). \quad (49)
 \end{aligned}$$

Hence,

$$\begin{aligned}
 d(x_{n_k+1}, \Gamma x^*) &\leq \alpha(x_{n_k}, x_{n_k+1}), \alpha(x^*, \Gamma x^*)d(x_{n_k+1}, \Gamma x^*) \\
 &< K(x_{n_k}, x^*) + LQ(x_{n_k}, x^*). \quad (50)
 \end{aligned}$$

Also, where

$$\begin{aligned}
 K(x_{n_k}, x^*) &= \max\{d(x_{n_k}, x^*), \frac{[1 + d(x_{n_k}, \Gamma x_{n_k})]d(x^*, \Gamma x^*)}{1 + d(x_{n_k}, x^*)} \\
 &\quad \frac{[1 + d(x_{n_k}, \Gamma x^*)]d(x^*, \Gamma x_{n_k})}{1 + d(x_{n_k}, x^*)}\} \\
 &= \max\{d(x_{n_k}, x^*), \frac{[1 + d(x_{n_k}, x_{n_k+1})]d(x^*, \Gamma x^*)}{1 + d(x_{n_k}, x^*)}, \\
 &\quad \frac{[1 + d(x_{n_k}, \Gamma x^*)]d(x^*, x_{n_k+1})}{1 + d(x_{n_k}, x^*)}\}. \quad (51)
 \end{aligned}$$

and

$$\begin{aligned}
 Q(x_{n_k}, x^*) &= \min\{d(x_{n_k}, \Gamma x_{n_k}), d(x^*, \Gamma x^*), d(x_{n_k}, \Gamma x^*), d(x^*, \Gamma x_{n_k}), \\
 &\quad \frac{d(x_{n_k}, \Gamma x^*)d(x^*, \Gamma x_{n_k})}{1 + d(x_{n_k}, x^*)}, \frac{d(x_{n_k}, \Gamma x^*)d(x^*, \Gamma x^*)}{1 + d(x_{n_k}, x^*)}\} \\
 &= \min\{d(x_{n_k}, x_{n_k+1}), d(x^*, \Gamma x^*), d(x_{n_k}, \Gamma x^*), d(x^*, x_{n_k+1}), \frac{d(x_{n_k}, \Gamma x^*)d(x^*, x_{n_k+1})}{1 + d(x_{n_k}, x^*)}, \\
 &\quad \frac{d(x_{n_k}, \Gamma x^*)d(x^*, \Gamma x^*)}{1 + d(x_{n_k}, x^*)}\}. \quad (52)
 \end{aligned}$$

Taking $k \rightarrow \infty$ in the equation(50) and(51) we derive that

$$K(x_{n_k}, x^*) = d(x^*, \Gamma x^*) \text{ and } Q(x_{n_k}, x^*) = 0. \quad (53)$$

From (50) ,by using (53), we get

$$d(x_{n_k+1}, \Gamma x^*) < d(x^*, \Gamma x^*) \text{ for all } k \in \mathbb{N} \quad (54)$$

By (49), (54), and the condition (ζ_3), we have

$$0 \leq \limsup_{n \rightarrow \infty} \zeta(\alpha(x_{n_k}, \Gamma x_{n_k}), \alpha(x^*, \Gamma x^*), d(\Gamma x_{n_k}, \Gamma x^*)K(x_{n_k}, x^*) + LQ(x_{n_k}, x^*)) < 0.$$

This is contradiction.Hence therefore, x^* is a fixed point of Γ . Now ,assume that, there exists $x^*, y^* \in X$ such that $x^* = \Gamma x^*$ and $y^* = \Gamma y^*$ with $x^* \neq y^*$. Since Γ is Generalized α -admissible modified almost z contraction selfmapping of a metric space (X, d) . So by assumption (iv) from Theorem 2.3, we hav

$$\alpha(x^*, y^*) \geq 1. \quad (55)$$

Therefore, from (10) and $|\zeta_2$ that,

$$\begin{aligned}
 0 &\leq \zeta(\alpha(x^*, \Gamma x^*), \alpha(y^*, \Gamma y^*)d(\Gamma x^*, \Gamma y^*), K(x^*, y^*) + LQ(x^*, y^*)) \\
 &= \zeta(\alpha(x^*, x^*), \alpha(y^*, y^*), d(x^*, y^*)K(x^*, y^*) + LQ(x^*, y^*)) \\
 &< K(x^*, y^*) + LQ(x^*, y^*) - \alpha(x^*, x^*), \alpha(y^*, y^*), d(x^*, y^*) \quad (56)
 \end{aligned}$$

Also , where

$$\begin{aligned} K(x^*, y^*) &= \max \left\{ d(x^*, y^*) \frac{[1 + d(x^*, x^*)]d(y^*, y^*)}{1 + d(x^*, y^*)}, \frac{[1 + d(x^*, y^*)]d(y^*, x^*)}{1 + d(x^*, y^*)} \right\} \\ &= \max \{d(x^*, y^*), d(Y^*, x^*)\} \\ &= d(x^*, y^*) \end{aligned} \quad (57)$$

and

$$\begin{aligned} Q(x^*, y^*) &= \min \{d(x^*, x^*), d(y^*, y^*), d(x^*, y^*), d(y^*, x^*), \frac{d(x^*, y^*)d(y^*, x^*)}{1 + d(x^*, y^*)}, \\ &\quad \frac{d(x^*, x^*)d(y^*, y^*)}{1 + d(x^*, y^*)}\} \\ &= \min \left\{ 0, 0, d(x^*, y^*), d(y^*, x^*), \frac{d(x^*, y^*)d(y^*, x^*)}{1 + d(x^*, y^*)}, 0, \right\} \\ &= 0. \end{aligned} \quad (58)$$

From (56) together with (57) and (58), we deduce that

$$0 < d(x^*, y^*) \leq \alpha(x^*, x^*), \alpha(y^*, y^*)d(x^*, y^*) < d(x^*, y^*).$$

this is contradiction. Thus , we have $x^* = y^*$. Hence, Γ has a unique fixed point. \square

Corollary 2.4. *Let (X, d) be a metric space, $\Gamma : X \rightarrow X$ is a generalized α -admissible modified almost z - contraction self mapping. There exists $\zeta \in Z$ and $\alpha : X \times X \rightarrow [0, \infty)$ be a function with $\alpha(x, \Gamma x) = 1$,and $\alpha(y, \Gamma y) = 1$, for all $x, y \in X$ such that*

$$\zeta(d(\Gamma x, \Gamma y)K(x, y) + LQ(x, y) \geq 0, \text{ for all } x, y \in X, \text{ and } L \geq 0,$$

Also where

$$K(x, y) = \max \left\{ d(x, y), \frac{[1 + d(x, \Gamma x)]d(y, \Gamma y)}{1 + d(x, y)}, \frac{[1 + d(x, \Gamma y)]d(y, \Gamma x)}{1 + d(x, y)} \right\}$$

and

$$Q(x, y) = \min \left\{ d(x, \Gamma x), d(y, \Gamma y), d(x, \Gamma y), d(y, \Gamma x), \frac{d(x, \Gamma y)d(y, \Gamma x)}{1 + d(x, y)}, \frac{d(x, \Gamma x)d(y, \Gamma y)}{1 + d(x, y)} \right\}.$$

Then Γ has a unique fixed point $x^* \in X$.

Corollary 2.5. *Let (X, d) be a metric space, $\Gamma : X \rightarrow X$ is a generalized α -admissible modified almost z - contraction self mapping. There exists $\zeta \in Z$ and $\alpha : X \times X \rightarrow [0, \infty)$ be a function with $\alpha(x, \Gamma x) = 1$, $\alpha(y, \Gamma y) = 1$, and $Q = 0$. for all $x, y \in X$ such that*

$$\zeta(d(\Gamma x, \Gamma y)K(x, y) \geq 0, \text{ for all } x, y \in X, \text{ and } L \geq 0,$$

Also where

$$K(x, y) = \max \left\{ d(x, y), \frac{[1 + d(x, \Gamma x)]d(y, \Gamma y)}{1 + d(x, y)}, \frac{[1 + d(x, \Gamma y)]d(y, \Gamma x)}{1 + d(x, y)} \right\}$$

Then Γ has a unique fixed point $x^* \in X$.

Example 2.6. Let $[0, 4]$ be endowed with metric space $d(x, y) = |x - y|$ for all $x, y \in X$ and $\Gamma : X \rightarrow X$ be defined by $\Gamma x = 4 - x$. Consider $\zeta(t, s) = \alpha s - t$, where $\alpha \in [0, 1)$, for all $t \geq 0$ and $L \geq 0$ and $\alpha : X \times X \rightarrow [0, \infty)$ be defined by

$$\alpha(x, y) = \begin{cases} 1 & \text{if, } x, y \in [0, 1] \\ 0, & \text{otherwise} \end{cases}$$

Note that Γ is triangular α -orbital admissible if $\alpha(x, \Gamma x) \geq 1 \Rightarrow \alpha(\Gamma x, \Gamma^2 x) \geq 1$, and $\alpha(x, y) \geq 1$ and $\alpha(y, \Gamma y) \Rightarrow \alpha(x, \Gamma y) \geq 1$. Since $\alpha(x, y) > 1$ and $x, y \in [0, 1]$. Then, we have $\alpha(x, \Gamma x) = \alpha(x, 4) = 1$ and $\alpha(y, \Gamma y) = 1$ for all $x, y \in X$.

In fact, for all $x \neq y$, then we have

$$\begin{aligned} \zeta(d(\Gamma x, \Gamma y)d(x, y)) &= \alpha|x - y| - |4 - x - (4 - y)| \\ &= \alpha|x - y| - |x - y| \\ &< |x - y| - |x - y| \\ &= 0 \end{aligned}$$

Now we show that Γ is a generalized α admissible modified almost z -contraction with respect to $\zeta \in Z$. Now

$$\begin{aligned} \zeta(d(\Gamma x, \Gamma y)K(x, y)) + LQ(x, y) &= K(x, y) + LQ(x, y) - d(\Gamma x, \Gamma y) \\ &= \alpha[|K(x, y) + LQ(x, y)|] - |4 - x - (4 - y)|, \\ &= \alpha[|K(x, y) + LQ(x, y)|] - |x - y|, \end{aligned}$$

where

$$\begin{aligned} K(x, y) &= \max \left\{ |x - y|, \frac{[1 + |x - (4 - x)|] |y - (4 - y)|}{1 + |x - y|}, \frac{[1 + |x - (4 - y)|] |y - (4 - x)|}{1 + |x - y|} \right\} \\ &= \max \left\{ |x - y|, \frac{[1 + |2x - 4|] |2y - 4|}{1 + |x - y|}, \frac{[1 + |x - 4 + y|] |y - 4 - x|}{1 + |x - y|} \right\} \end{aligned}$$

and,

$$\begin{aligned} Q(x, y) &= \min \{ |x - (4 - x)|, |y - (4 - y)|, |x - (4 - y)|, |y - (4 - x)|, \frac{|x - (4 - y)| \cdot |y - (4 - x)|}{1 + |x - y|} \\ &\quad \frac{|x - (4 - y)| \cdot |y - (4 - x)|}{1 + |x - y|} \} \\ &= \min \left\{ |2x - 4|, |2y - 4|, |x + y - 4|, \frac{|x + y - 4|}{1 + |x - y|}, \frac{|2x - 4| \cdot |2y - 4|}{1 + |x - y|} \right\}. \end{aligned}$$

We deduce that

$$\begin{aligned} \zeta(d(\Gamma x, \Gamma y)K(x, y)) + LQ(x, y) &= \alpha \left[\max \left\{ |x - y|, \frac{[1 + |2x - 4|] |2y - 4|}{1 + |x - y|}, \frac{[1 + |x + y - 4|] |x + y - 4|}{1 + |x - y|} \right\} \right. \\ &\quad \left. + L \min \left\{ |2x - 4|, |2y - 4|, |x + y - 4|, \frac{|x + y - 4|}{1 + |x - y|}, \frac{|2x - 4| \cdot |2y - 4|}{1 + |x - y|} \right\} \right] \\ &\quad - |x - y|. \end{aligned}$$

Hence, we get two cases:

Case(i): If $x = y$, then,

$$\begin{aligned} \zeta(d(\Gamma x, \Gamma y)K(x, y)) + LQ(x, y) &= \alpha \{ [1 + |2x - 4|] |2x - 4|, [1 + |2x - 4|] |2x - 4| \} \\ &\quad + L \{ |2x - 4|, |2y - 4|, |2x - 4|, |2x - 4|, |2x - 4| \cdot |2y - 4| \}; \\ &= \alpha \{ [1 + |2x - 4|] |2x - 4| + L |2x - 4| \} \geq 0. \end{aligned}$$

Case(ii): Without loss of generality, suppose that $x > y$, then

$$\begin{aligned} \zeta(d(\Gamma x, \Gamma y)K(x, y)) + LQ(x, y) &= \alpha \left[\left\{ \frac{[1 + |2x - 4|] |2y - 4|}{1 + |x - y|}, \frac{[1 + |2x - 4|] |2y - 4|}{1 + |x - y|} \right\} \right. \\ &\quad \left. + L \left\{ |2y - 4|, |2y - 4|, |2y - 4|, \frac{|2y - 4|}{1 + |x - y|}, \frac{|2y - 4| \cdot |2y - 4|}{1 + |x - y|} \right\} \right] \\ &\quad - |x - y|. \\ &= \alpha \frac{[1 + |2x - 4|] |2y - 4|}{1 + |x - y|} + \alpha L |2y - 4| - |x - y|. \end{aligned}$$

If $\alpha = \frac{1}{2}$ and $L = 10$, then we get

$$\zeta(d(\Gamma x, \Gamma y)K(x, y)) + LQ(x, y) = \frac{1}{2} \frac{[1 + |2x - 4|] |2y - 4|}{1 + |x - y|} + 5 |2y - 4| - |x - y|. \quad (59)$$

Therefore, Γ is generalized α admissible modified almost z -contraction with respect to $\zeta \in Z$. Hence, all the assumptions of Theorem 2.2 with Corollary 2.4 and Corollary 2.5 are satisfied. hence, Γ has a unique fixed point.

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