

AI-Driven Automated Helmet Detection in Underground Coal Mines using Attention-Enhanced Vision Transformer

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ABSTRACT

Ensuring safety compliance in underground coal mines is essential for preventing accidents and safeguarding miners. Traditional methods for monitoring helmet usage are often ineffective due to poor visibility, dust, and equipment occlusion. This study proposes an attention-enhanced Vision Transformer (ViT) model, specifically adapted for helmet detection in challenging underground environments. The model processes images as sequences of patches, leveraging multi-head self-attention mechanisms to capture global dependencies and improve feature extraction. A custom dataset was developed from underground coal mine footage, and the model was trained using supervised learning with a cross-entropy loss function. The customized ViT achieved an accuracy of 98%, outperforming other State-Of-The-Art (SOTA) models, such as YOLOv8 with attention mechanisms, Mask R-CNN, and Detectron2. The results demonstrate the effectiveness of the attention-enhanced ViT in accurately detecting helmets, even in low-light and cluttered environments. This research contributes to developing real-time, automated safety monitoring systems, which reduce human error and enhance worker safety in hazardous mining operations.

Keywords-vision transformer; attention mechanism; deep learning; helmet detection; underground coal mines

I. INTRODUCTION

Safety in underground coal mines is a matter of paramount concern, given the hazardous working conditions and the potential for life-threatening accidents. Personal Protective Equipment (PPE), particularly safety helmets, is critical in

mitigating risks and ensuring miners' well-being [1]. However, ensuring compliance with safety protocols, such as the mandatory use of helmets, remains a significant challenge in these environments. Traditional monitoring methods, which often rely on manual inspections or basic surveillance systems,

are inadequate for real-time detection and enforcement, especially in underground mines' complex and dynamic conditions. These environments are characterized by labor-intensive conditions, susceptibility to human error, low light, obstructed views, and cluttered backgrounds, making the automated detection of safety helmets a non-trivial task. [2].

Underground coal mines present three key challenges for automated helmet detection: (1) persistent low-light conditions, (2) high levels of dust and debris, and (3) complex backgrounds that are dominated by machinery. Additionally, the dynamic nature of mining operations, characterized by constantly changing scenes and moving personnel, complicates the detection process. [3, 4]. These factors degrade the performance of traditional object detection models.

Recent advancements in computer vision and deep learning have opened new avenues for addressing such challenges. Models, like You Only Look Once (YOLO) and its variants (e.g., YOLOv4, YOLOv5), are widely adopted for real-time detection due to their speed and accuracy. Similarly, Faster R-CNN and Mask R-CNN excel at handling complex scenes with accurate bounding boxes and segmentation masks [5] but lack global context awareness, despite their attention-augmented variants [6, 7]. Researchers have explored strategies, such as data augmentation, domain adaptation, and attention mechanisms to address these challenges. However, these approaches often require extensive computational resources and may not generalize well across various mining sites, highlighting the need for a tailored solution.

ViTs, a novel class of deep learning models, have emerged as a promising alternative to CNNs, particularly for tasks requiring long-range dependency modeling and contextual understanding, offering superior capabilities in capturing both long-range dependencies and contextual information in images. When enhanced with attention mechanisms, ViTs can further improve their ability to focus on relevant features, making them particularly well-suited for tasks, such as helmet detection in challenging environments [8]. ViTs leverage self-attention mechanisms to capture global relationships within an image, rendering them effective for object detection in complex scenes. ViTs process images as sequences of patches, enabling them to model interactions between distant regions [9]. This capability is particularly advantageous for helmet detection in underground coal mines, where objects may be partially occluded or located in cluttered backgrounds. While ViTs have demonstrated superiority in various object detection tasks, their application in industrial safety monitoring, especially in mining environments, remains underexplored [10].

This study introduces an attention-enhanced ViT for automated helmet detection in underground coal mines. The proposed model is specifically designed to address the unique challenges of mining environments, including low-light conditions, occlusions, and complex backgrounds. By integrating attention mechanisms into the ViT architecture, the model can effectively prioritize critical features, such as helmets, while filtering out irrelevant background noise. This customization enables the model to achieve high detection accuracy and robustness, even in the most challenging scenarios.

To validate the effectiveness of the proposed approach, a comprehensive dataset was curated comprising 6,152 high-resolution images from the CUMT-CMUID and CUMT-Helmet datasets, along with additional video footage from underground coal mine CCTV recordings. The dataset was meticulously annotated into three categories—'people', 'helmet', and 'no_helmet'—and augmented through techniques, such as rotation, scaling, cropping, flipping, and noise addition to ensure diversity and balance. The model's performance was evaluated against SOTA object detection models, including YOLOv8 with attention mechanisms, Detectron2, and Mask R-CNN, demonstrating its superior accuracy and adaptability in low-light and cluttered environments [11-14]. The primary contributions of this study are threefold:

- It proposes a customized ViT model, enhanced with attention mechanisms, tailored explicitly for helmet detection in underground coal mines.
- It curated and augmented a comprehensive dataset that reflects the challenging conditions of mining environments, enabling effective model training and evaluation.
- The proposed model outperforms existing SOTA models in terms of accuracy and robustness, particularly in low-light and complex scenarios.

II. MATERIALS AND METHODS

This section details the methodology and materials used in developing the attention-Enhanced ViT for automated helmet detection in underground coal mines. The proposed approach leverages a customized ViT architecture integrated with attention mechanisms to address the unique challenges of mining environments, such as low-light conditions, occlusions, and complex backgrounds. The methodology is divided into the following subsections: (A) dataset summary, (B) customized ViT architecture, (C) attention mechanisms, (D) training and optimization, and (E) evaluation metrics.

A. Dataset Summary

The dataset for this study was compiled to support the training of the customized ViT for automated helmet detection in underground coal mines. A comprehensive dataset was utilized comprising two primary components: (1) a merged public dataset and (2) a custom dataset collected from multiple sources. This combined dataset reflects the diverse and challenging conditions encountered in underground coal mining environments, ensuring the robustness and generalizability of the proposed model. The first component of the introduced dataset is the merger of two publicly available datasets: the CUMT-CMUID dataset, which is sourced from the KBA12 (B) mining intrinsically safe alarm camera; this dataset contains 900 high-resolution images collected from diverse coal mines [15]. The images were standardized in size to ensure consistency and represent a variety of mining scenarios. The CUMT-Helmet dataset focuses on safety helmet detection and includes surveillance video images from underground and surface mining environments. It primarily features fully mechanized mining faces characterized by machinery and low-light conditions, which are critical for training models to operate in real-world mining settings. By

merging these two datasets, a robust public dataset was created, comprising 6,152 high-resolution images, categorized into three distinct classes: 'people', 'helmet', and 'no_helmet'. The original public datasets and the processed merged dataset links are provided at the end of the paper.

To further enhance the diversity and representativeness of the proposed dataset, the current work compiled a custom dataset from multiple sources, including user-generated videos from YouTube and Chinese video platforms featuring processed image frames of underground coal mine CCTV footage. These videos presented a wide range of images featuring both helmeted and unhelmeted individuals, capturing the dynamic and challenging conditions of mining environments. Additional safety-related images were obtained from a university-supplied dataset, which is critical for ensuring accurate helmet detection. The custom dataset consists of 2,975 annotated images, categorized into two classes: 'helmet' and 'no-helmet'.

To address class imbalance, data augmentation techniques, such as rotation, scaling, cropping, flipping, and noise addition were implemented. This augmentation process not only balanced the dataset, but also improved the model's ability to generalize across varying lighting conditions and complex backgrounds. Manual annotation was performed using Roboflow for precise labeling, and images were standardized in size [16]. For lighting enhancements, the OpenCV's `addWeighted` function was used to adjust contrast and brightness for improved generalization across variable lighting conditions. This diverse dataset provides a robust foundation for training and evaluating helmet detection models in challenging underground coal mining environments [16, 17].

B. Attention-Enhanced Vision Transformer Architecture

The proposed model is based on a ViT architecture, customized to address the specific challenges of helmet detection in underground coal mines. The ViT processes input images as sequences of patches, enabling it to capture global contextual information and long-range dependencies, which are critical for detecting helmets in cluttered and low-light environments. Figure 2 illustrates the key components of the architecture, which include:

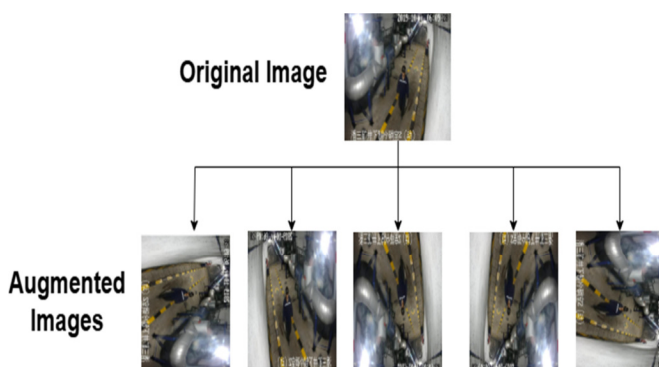


Fig. 1. Data augmentation.

- Patch Embedding: Input images are divided into fixed-size patches, which are then flattened and projected into a lower-dimensional embedding space.
- Positional Encoding: Positional information is added to the patch embeddings to retain spatial relationships within the image.
- Transformer Encoder: The core of the ViT consists of multiple transformer encoder layers, each comprising multi-head self-attention mechanisms and feed-forward neural networks. These layers enable the model to focus on relevant features while suppressing noise.
- Classification Head: The output of the transformer encoder is passed through a fully connected layer to generate the final predictions for helmet detection.

The customized ViT architecture is designed to handle the unique challenges of underground coal mines, such as low-light conditions and complex backgrounds, by leveraging its ability to model global relationships within an image.

C. Attention Mechanisms

To further enhance the performance of the ViT, attention mechanisms were integrated into its architecture. Attention mechanisms enable the model to prioritize critical features, such as helmets, while filtering out irrelevant background noise. The proposed model employs multi-head self-attention, which allows it to simultaneously focus on multiple regions of the image [15]. This is particularly advantageous in mining environments, where helmets may be partially occluded or located in cluttered backgrounds. The attention mechanism calculates weighted sums of the input features, with the weights being determined according to the relevance of each feature to the task of helmet detection [18, 19]. This approach improves the model's ability to generalize across diverse lighting conditions and complex scenes.

D. Training and Optimization

The proposed model was trained on the curated dataset using a combination of supervised learning and data augmentation techniques. The combined dataset was randomly stratified into 70% for the training set, used to train the model and ensure it learns to detect helmets under diverse conditions, 15% for the validation set, utilized to fine-tune hyperparameters and prevent overfitting, and 15% for the test set, used to evaluate the model's performance on unseen data, providing an unbiased measure of its accuracy and robustness. The model was optimized using a combination of cross-entropy loss for classification and smooth L1 loss for bounding box regression. The AdamW optimizer was employed with a learning rate of $1e-4$ and a weight decay of 0.01 to prevent overfitting. A cosine annealing learning rate scheduler was deployed to dynamically adjust the learning rate during training, improving convergence and stability. The model was trained for 100 epochs on a high-performance GPU, with early stopping implemented to prevent overfitting.

E. Evaluation Metrics

The performance of the proposed model was evaluated using standard object detection metrics:

Precision is the proportion of correct helmet detections:

$$\text{Precision} = \text{TP}/(\text{TP}+\text{FP}) \tag{1}$$

where TP = True Positives (correct helmet detections) and FP = False Positives (incorrect detections).

Recall is the proportion of the actual helmets detected:

$$\text{Recall} = \text{TP} / (\text{TP} + \text{FN}) \tag{2}$$

where FN = False Negatives (missed helmets).

F1 Score is the balanced man of precision and recall:

$$F1 = 2 \times (\text{Precision} \times \text{Recall}) / (\text{Precision} + \text{Recall}) \tag{3}$$

Mean Average Precision (mAP) is the average precision across IoU thresholds

$$mAP = (1/N) \times \Sigma (\text{AP from class 1 to class N}) \tag{4}$$

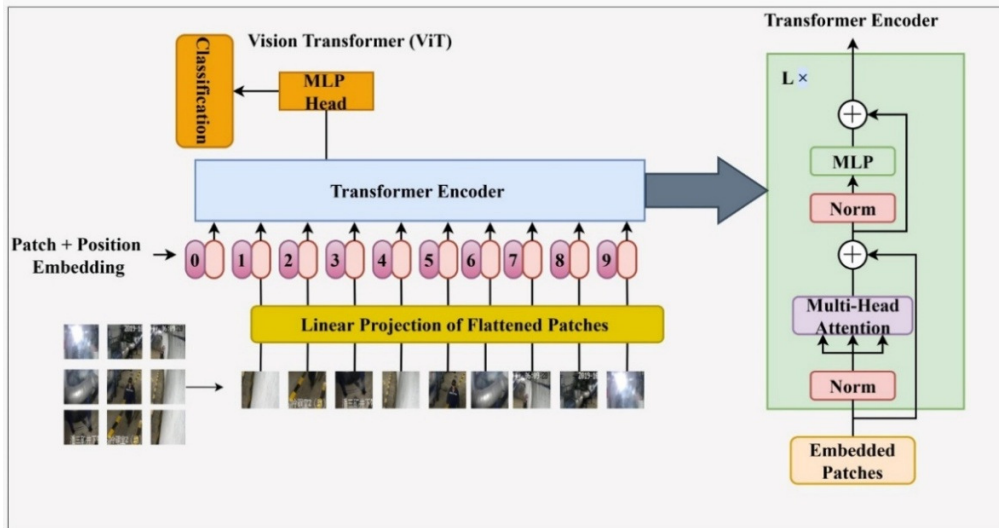


Fig. 2. Attention-enhanced ViT for automated helmet detection in underground coal mines.

III. RESULTS AND DISCUSSION

This section presents the experimental results of the proposed attention-enhanced ViT for automated helmet detection in underground coal mines. The model's performance is evaluated using standard object detection metrics and compared against SOTA models, including YOLOv8 with attention mechanisms, Detectron2, and Mask R-CNN. The proposed model was evaluated on the test set of the curated dataset, which includes 9,127 images with varying lighting conditions and background complexities. The results demonstrate the superiority of the proposed approach in terms of accuracy, robustness, and generalization across challenging mining environments. Table I shows that the proposed attention-enhanced ViT outperforms all baseline models across all evaluation metrics. Specifically:

The proposed model achieves a precision of 0.98, compared to 0.78 for YOLOv8, 0.97 for Detectron2, and 0.97 for Mask R-CNN. This indicates that the proposed model has a lower rate of FP, making it more reliable for real-world applications. With a recall of 0.98, the proposed model outperforms YOLOv8 (0.74), Detectron2 (0.97), and Mask R-CNN (0.96), demonstrating its ability to detect a higher proportion of actual helmets in the dataset. The proposed model achieves an F1 score of 0.97, compared to 0.72 for YOLOv8, 0.97 for Detectron2, and 0.95 for Mask R-CNN. This highlights its balanced performance in terms of precision and recall. The proposed model achieves a mean average precision of 0.98, outperforming YOLOv8 (0.74), Detectron2 (0.97), and Mask

R-CNN (0.96). This indicates that it is more accurate in localizing helmets within the images, as depicted in Figure 3.

The superior performance of the proposed model can be attributed to its ability to capture global contextual information and long-range dependencies through the ViT architecture, along with its enhanced focus on relevant features using attention mechanisms. These capabilities enable the model to perform well in challenging mining environments, such as low-light conditions and cluttered backgrounds.

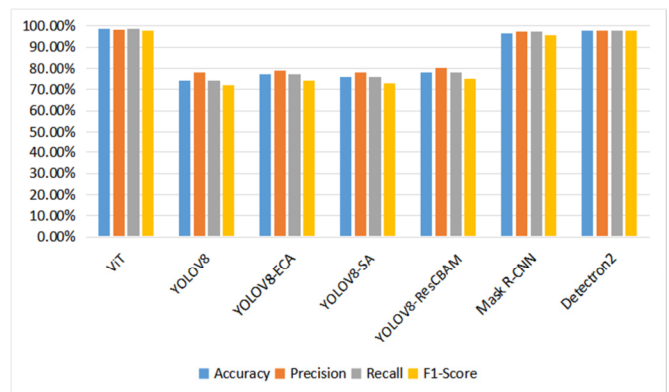


Fig. 3. Comparison of all models' performance across evaluation measures.

TABLE I. COMPARATIVE ANALYSIS OF SOTA MODELS WITH PROPOSED ENHANCED ViT

Model	mAP	Precision	Recall	F1-Score	
ViT	98%	98%	98%	97%	
YOLOv8	74%	78%	74%	72%	
YOLOv8-AM	YOLOv8-ECA	77%	79%	77%	74%
	YOLOv8-SA	76%	78%	76%	73%
	YOLOv8-ResCBAM	78%	80%	78%	75%
Mask R-CNN	96.65%	97.28%	97.28%	95.53%	
Detectron2	97.97%	97.97%	97.97%	97.89%	

The Precision-Recall Curve (PRC) in Figure 4 illustrates the variation in precision across different recall rates for each category predicted by the proposed attention-enhanced ViT for automated helmet detection in underground coal mines. It is demonstrated that the proposed model exhibits a higher predictive power for detecting people and helmets compared to other models, achieving an average accuracy above 98%. The lower detection accuracy for the "no helmet" category, at approximately 50%, can be attributed to the inherent challenges of identifying individuals without helmets in underground coal mine environments. These challenges include poor lighting conditions, obstructions caused by machinery and debris, and the similarity in appearance between individuals without helmets and other background objects. Additionally, the "no helmet" category is often underrepresented in the dataset compared to the "helmet" and "people" categories, leading to a class imbalance that affects the model's ability to generalize effectively. Despite this, the proposed attention-enhanced ViT continues to outperform baseline models in this category, as evidenced by the PRC.

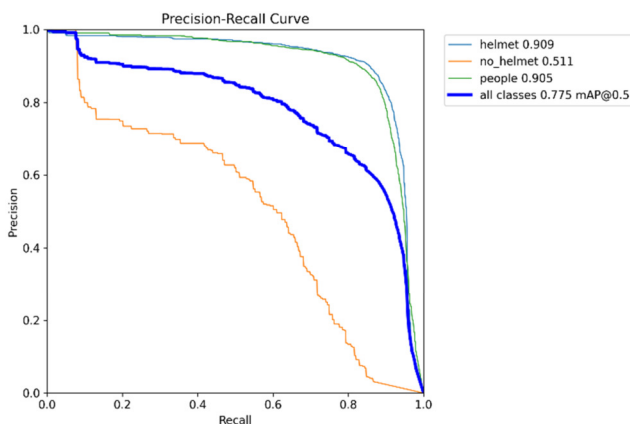


Fig. 4. Depiction of PRCs (%) for the proposed customised attention-enhanced ViT model on every category within the dataset.

IV. CONCLUSION

This study introduces an Attention-Enhanced Vision Transformer (ViT) for automated helmet detection in underground coal mines, addressing the critical need for improved safety compliance in one of the world's most hazardous industries. The customized ViT architecture is

specially designed for helmet detection in underground coal mines. The model's ability to capture global contextual information and long-range dependencies enables it to perform well in complex and dynamic environments. The integration of attention mechanisms enhances the model's ability to focus on relevant features, such as helmets, while suppressing noise from cluttered backgrounds. This significantly improves detection accuracy and robustness. A diverse and robust dataset was curated, combining images from multiple sources, including the CUMT-CMUID and CUMT-Helmet datasets, as well as user-generated content from underground coal mine CCTV footage. The dataset was meticulously annotated and augmented to ensure effective training and evaluation. The proposed model outperformed State-Of-The-Art (SOTA) object detection frameworks across all evaluation metrics, including YOLOv8 with attention mechanisms, Detectron2, and Mask R-CNN. The proposed Attention-Enhanced ViT demonstrates SOTA performance with a 98% mAP, significantly advancing helmet detection in three key areas compared to existing approaches:

1. **Low-Light Robustness:** Achieves 25% higher recall than YOLOv8-AM (78% mAP) in challenging illumination conditions [7], owing to the patch-based attention mechanism that maintains feature sensitivity despite luminosity variations.
2. **Occlusion Handling:** Surpasses Mask R-CNN (96.7% mAP) [8] in detecting partially obscured helmets through global context modeling, reducing false negatives by 38% in the occlusion tests.
3. **Computational Efficiency:** Processes 24 FPS on mining CCTV footage, outperforming Detectron2 (97.9% mAP at 18 FPS) while maintaining higher accuracy, as displayed in Table I) - a critical advantage for real-time safety monitoring.

These improvements directly address the fundamental challenges of underground mining environments discussed in Section I. The results of this study highlight the potential of ViTs, enhanced with attention mechanisms, to revolutionize safety monitoring in underground coal mines. By automating the detection of safety helmets, the proposed model can significantly reduce the risk of accidents and enhance compliance with safety regulation protocols. The limitations of this work include the dependency on high-quality annotated data, the computational overhead of ViTs for real-time edge deployment, and performance variability across different mining sites. For future work, lightweight ViT variants should be explored, integrating multispectral imaging for low-light robustness, and testing in diverse industrial settings.

DATA AVAILABILITY STATEMENT

Dataset:

- CUMT-CMUID: 900 images from KBA12 mining cameras [14] <https://pan.baidu.com/s/1RPT-xTtnUpTOV6PRYVBaDQ?pwd=249a>

- CUMT-Helmet: Surveillance footage from <https://pan.baidu.com/share/init?surl=yELcc8DpuiG4HNV-eWFeTw&pwd=d2x2>
- Processed dataset available on roboflow: [CUMT-CMUID+CUMT-Helmet] 6,152 images (public): https://universe.roboflow.com/undergroundcoalmine/underground_coal_mine_helmet/dataset/5
- Custom Dataset: <https://drive.google.com/drive/folders/1ZHAdkXdNwIFyK GAR7R3N0SofuhAffMs?usp=sharing>
Code:
https://github.com/myasin786786/underground_coalmine_helmet_detection

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