Effect Evaluation of Fault Resistance on the Operating Behavior of a Distance Relay

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Abstract—This paper presents an application of a certain distance protection relay with a quadrilateral characteristic approach for the protection of the 110kV Duy Xuyen - Thang Binh transmission line in Vietnam using measured data from one terminal line. We propose the building process of a Matlab Simulink model for this relay that combines fault detection and classification block, apparent impedance calculation block for all types of faults and a trip logic block of three zone protection coordination. The proposed relay model is further tested using various fault scenarios on the transmission line. It is important to assess what happened, the actual conditions, the causes of maloperation etc. Detailed explanation and results indicate that the proposed model behavior will help users to perform tests which correctly simulate real-world conditions besides that it properly interprets test results and troubleshoot distance function problems when results are not as expected.

Keywords-transmission line; distance protection relay; quadrilateral characteristic; logic trip; Matlab/Simulink

I. INTRODUCTION

Transmission lines are one of the main components in high voltage and extra high voltage power system. The main protection used to protect Vietnam's transmission lines is a numerical distance protection relay (F21) as shown in Figure 1 because of its suitability, simplicity, economy, and reliability. There are now various distance relays that have been implemented by different vendors. These relays help to protect safeguard transmission line from exposure to any type of faults (internal or external) which could intentionally or inadvertently damage electrical equipment and avoid a great effect on the stability of the entire power system. However, the distance protection also faces a number of factors which influence negatively its operation, and thus affect its accurate determination of the measured impedance. This then results in inaccurate fault location determination [1]. A relay device manufacturer, or a power system operator, needs to conduct a simulated use of all test scenarios due to factors such as human factor, fault resistance and load current, coupling of parallel lines, multiple feeder sections, power swing or multi-end sources testing to evaluate the operating behavior of relay's characteristics. Many operators are uncertain about the advantages and disadvantages of mho or quadrilateral characteristic related to fault type, system conditions, and look

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up the backgrounds of the mal-operation to remove errors. In practice, the relay provides satisfactory results for the operation condition of low resistance faults. But, in the case of high resistance faults, particularly for single phase to earth faults, it measures an incorrect value of fault impedance. Consequently, the relay may over-reach or under-reach depending upon the forward/backward flow direction and the magnitude of fault resistance [2]. In order to prove this issue, the current paper focuses on the algorithm of Siemens 7SA522 relay that uses a quadrilateral characteristic. Thereafter, the 110kV Duy Xuyen - Thang Binh transmission line model is selected as an example of fault simulation and the algorithm relay is tested in Simulink. The proposed model has been assessed under several scenarios. Conclusions based on the results are discussed along with the resistance fault factor affecting the relay's accuracy.



Fig. 1. Distance protection relay on transmission line

II. RELAY PROTECTION ZONES

In [3, 4], the disadvantage of the Mho relay is that, when it is used on long lines and the reach does not cover the section sufficiently along the resistance axis, it is incapable of detecting faults with high arc or fault resistances. The problem is aggravated in the case of short lines since the setting is low and the amount of the R axis covered by the mho circle is small in relation to the expected values of arc resistance. So that, the quadrilateral characteristic is a good choice to overcome the disadvantages of mho element when it is properly designed. In the case of medium lines, earth faults can, for instance, be covered with the quadrilateral characteristic and phase faults with the mho characteristic.

In Vietnam, the 110kV Duy Xuyen-Thang Binh transmission line has length less than 30 km and, as shown in

Figure 2, is protected by a Siemens 7SA522 distance protection relay with three forward quadrilateral zones (Z1, Z2, Z3) which provide fault impedance coverage for both phase to phase and phase to earth faults. Setting calculation is important in protection zone setup, so human error can affect the accuracy of the relay protection besides the large amounts of faults to be collected and processed. The transmission line parameter (Line length=29 km, Line angle=68°, line reactance=0.3304 Ω /km), Zero sequence compensation factor ($R_F/R_I=0.29$, $X_F/X_I=0.67$), and fault resistance must also be taken into account. The zone settings of this transmission line are calculated by the central region load dispatch center in Vietnam ensuring that they are properly coordinated with the adjacent system and comply with the existing guidelines. The three zones of guadrilateral characteristic used to protect transmission line are explained in Table I [5]. We used the DIGSI operating software to enter configuration settings in the relay, it can automatically draw a relay operating characteristic graph as shown in Figure 3. The quadrilateral characteristic permits separate setting of the reactance X and the resistance R. The resistance section R can be set separately for faults with and without earth involvement, therefore, this characteristic has an optimal performance in case of faults with fault resistance [6]. The effect of fault resistance on the reach of distance relays is better discussed with the simulation results.



Fig. 2. The 110kV power system

 TABLE I. PARAMETER SETTING ON SIEMENS 7SA522 ON A 110KV DUY

 XUYEN-THANG BINH OVERHEAD LINE

Zone	Relay Setting			
	Setting	Value		
Zone 1	Covers 85%AB, forward direction (0.85ZAB)	Operating Mode Z1: Forward X(Z1), Rectance: 8.14Ω R(Z1), Resistance for Ph-Ph faults: 30Ω RE(Z1), Resistance for Ph-E faults: 40Ω tZ1, Delay for fault: 0s		
Zone 2	Covers 100%AB + 60%BC, forward direction (ZAB + 0.6ZBC)	Operating Mode Z2: Forward X(Z2), Rectance: 11.5Ω R(Z2), Resistance for Ph-Ph faults: 35Ω RE(Z2), Resistance for Ph-E faults: 50Ω tZ2, Delay for fault: 0.3s		
Zone 3	Covers 100%AB + 100%BC + 60%CD, forward direction (ZAB + ZBC + 0.6ZCD)	Operating Mode Z3: Forward X(Z3), Rectance: 19.53Ω R(Z3), Resistance for Ph-Ph faults: 40Ω RE(Z3), Resistance for Ph-E faults: 55Ω tZ3, Delay for fault: 1.5s		

III. POWER SYSTEM UNDER STUDY

We model the power system that is supplied from both ends as shown in Figure 4. It uses Simulink to evaluate the distance protection function. The overhead line is 89.65 km long, and the system nominal operating voltage is 110 kV, 50Hz.



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Fig. 3. Quadrilateral characteristic of Siemens 7SA522 at the 171 overhead line of Duy Xuyen Substation



This model consists of:

1. The transmission line: three phase section line is used to represent the transmission line. Line sequence impedance is:

$$\begin{split} R_{L1} &= 0.1335\Omega, \, R_{L0} &= 0.2496\Omega. \\ L_{1.1} &= 1.0517 \text{mH}, \, L_{L0} &= 3.1657 \text{mH}. \end{split}$$

C_{L1}=0.038µF, C_{L0}=0.038µF.

- 2. A load of 110 kV, 35 MW, and 50 kVAR is connected to the bus Duy Xuyen, Thang Binh, Thang Binh 2, Tam Thang.
- 3. Three phase fault block to deduce fault types and fault resistance varying from 1 to 40 ohms.
- 4. Three-phase measuring blocks to measure the three phase line, load current and voltage values.
- 5. The Scopes already support the display of five inputs (Voltages, Currents, Zones 1-3) of a simulated system, which allows a better signal comparison.
- A Siemens 7SA522 relay is located at bus Duy Xuyen. It has been developed for fault detection, fault location, and distance protection which will be presented in section IV.
 - IV. DISTANCE PROTECTION RELAY SIEMENS 7SA522 MODEL

The simulation model of the relay has been designed with four functional flow block diagrams (Figure 5) by using Matlab's Simulink library. Firstly, measurement block reads the values of voltage and current of each phase. Next, fault detection and classification are done by FD block and Fault_Type block. Thirdly, impedance calculation block computes the value of R_{CAL} and X_{CAL} . Afterwards, Trip_logic block checks operating logics. If all four conditions are repeated from start to end. This helps us monitor and analyze data to avoid severe misunderstanding in assessing any use issues that arose during testing.



Fig. 5. Distance protection model

A. Current and Voltage Measurement

The measurement block receives two input signals corresponding to the three phase voltages and currents from CT, VT and then it provides to the multiplexer to split the voltage and current signals into three single phase voltages and currents. After that, these quantities are passed through the Fourier transform block to avoid the higher order harmonics as shown in Figure 6.

B. Fault Detection and Fault Classification

According to the outputs of the measurement block (I_A , I_B , I_C , and I_N), the fault detection in the transmission line is defined by the FD block. For earth current measurement, the fundamental component of the sum of the numerically filtered

phase currents is supervised to detect if it exceeds the set value (parameter $3I0>0.5I_N$) then output "N" equals 1. For phase current measurement, a fault occurrence is detected if I_A , I_B , or I_C is greater than the threshold $1.3I_{Norm}$. Then output "A", or "B", or "C" is equal to 1 [7]. Based on the information above, fault_type block performs fault classifying on the transmission line which can be summarized as in Table II.



Fig. 6. Measurement block

TABLE II. FAULT TYPE CLASSIFICATION

No	Type fault	Α	В	С	Ν
1	AG	1	0	0	1
2	BG	0	1	0	1
3	CG	0	0	1	1
4	AB	1	1	0	0
5	BC	0	1	1	0
6	CA	1	0	1	0
7	ABG	1	1	0	1
8	BCG	0	1	1	1
9	CAG	1	0	1	1
10	ABC	1	1	1	

C. Impedance Calculation

To calculate the R_{CAL} , X_{CAL} of relay protection, it uses one of the six loop measurements (AG, BG, CG, AB, BC, and CA) listed in Table III. The measured fault loop is necessary to know the fault type, local voltages and currents along with the zero sequence compensation factors. The following equations are employed to evaluate the measured values [7]. For the calculation of the phase-to-earth loop, for example during an AG short-circuit (Figure 7) it must be noted that the impedance of the earth return path does not correspond to the impedance of the phase. In the faulted loop the voltage AG, the phase current I_A and the earth current I_E are measured. The impedance to the fault location results from:

$$R_{A} = \frac{U_{A}}{I_{A}} \frac{\cos(\varphi_{U} - \varphi_{A}) - \frac{I_{E}}{I_{A}} \frac{X_{E}}{X_{L}} \cos(\varphi_{U} - \varphi_{E})}{1 - (\frac{X_{E}}{X_{L}} + \frac{R_{E}}{R_{L}}) \frac{I_{E}}{I_{A}} \cos(\varphi_{E} - \varphi_{A}) + \frac{R_{E}}{R_{L}} \frac{X_{E}}{X_{L}} \left(\frac{I_{E}}{I_{A}}\right)^{2}}$$
(1)

$$X_{A} = \frac{U_{A}}{I_{A}} \frac{\sin(\varphi_{U} - \varphi_{A}) - \frac{I_{E}}{I_{A}} \frac{R_{E}}{R_{L}} \sin(\varphi_{U} - \varphi_{E})}{1 - (\frac{X_{E}}{X_{L}} + \frac{R_{E}}{R_{L}}) \frac{I_{E}}{I_{A}} \cos(\varphi_{E} - \varphi_{A}) + \frac{R_{E}}{R_{L}} \frac{X_{E}}{X_{L}} \left(\frac{I_{E}}{I_{A}}\right)^{2}}$$
(2)

TABLE III. SHORT CIRCUIT TYPES AND FAULT LOOPS FOR THE DISTANCE MEASUREMENT

No	Type fault	Phases involved	Fault loop for distance measurement
1	Single phase to ground fault	AG	AG
		BG	BG
		CG	CG
2	Two phase short circuit without ground	AB	AB
		BC	BC
		CA	CA
3	Two phase short circuit with ground	ABG	AG, or BG, or AB
		BCG	BG, or CG, or BC
		CAG	AG, or CG, or CA
4	Three phase short circuit	ABC	AB, or BC, or CA



Fig. 7. Single-phase earth fault, fault loop

In (1) and (2), U_A is the short-circuit voltage of phase A, I_A is the short-circuit current of phase A, I_E is the earth short-circuit current, ϕ_U is phase angle of the short-circuit voltage, ϕ_A is phase angle of the phase short-circuit current, and ϕ_E is phase angle of the earth short-circuit current. To calculate the phase-to-phase loop for instance during a two-phase short circuit BC (Figure 8), the loop equation is:

$$R_{BC} = \frac{U_B I_B \cos(\varphi_{U_B} - \varphi_{I_B}) + U_C I_C \cos(\varphi_{U_C} - \varphi_{I_C})}{I_B^2 - 2I_B I_C \cos(\varphi_{I_B} - \varphi_{I_C}) + I_C^2} - \frac{U_B I_C \cos(\varphi_{U_B} - \varphi_{I_C}) + U_C I_B \cos(\varphi_{U_C} - \varphi_{I_B})}{I_B^2 - 2I_B I_C \cos(\varphi_{I_B} - \varphi_{I_C}) + I_C^2}$$
(3)

$$X_{BC} = \frac{U_{B}I_{B}\sin(\varphi_{U_{B}} - \varphi_{I_{B}}) + U_{C}I_{C}\sin(\varphi_{U_{C}} - \varphi_{I_{C}})}{I_{B}^{2} - 2I_{B}I_{C}\cos(\varphi_{I_{B}} - \varphi_{I_{C}}) + I_{C}^{2}} - \frac{U_{B}I_{C}\sin(\varphi_{U_{B}} - \varphi_{I_{C}}) + U_{C}I_{B}\sin(\varphi_{U_{C}} - \varphi_{I_{B}})}{I_{B}^{2} - 2I_{B}I_{C}\cos(\varphi_{I_{B}} - \varphi_{I_{C}}) + I_{C}^{2}}$$
(4)



Fig. 8. Two-phase fault clear of earth, fault loop

In (3) and (4), I_B , and I_C represents short circuit phase current of phase B, and C. U_B , and U_C represents short circuit voltage of phase B, and C. ϕ_{UB} , ϕ_{UC} are considered as phase angle of U_B , U_C . ϕ_{IB} , ϕ_{IC} are considered as phase angle of I_B , I_C .

D. Logic Decision

As mentioned in the description of the calculation impedance, the calculated R_{CAL} and X_{CAL} coordinate values define a point on the complex impedance plane. The logic decision compares the point with the quadrilateral characteristics of the relay, shown in Figure 3. For example, the distance characteristic has been programmed as seen in Figure 9 [7]. The point R_3 and X_3 are the setting points for Zone 3. The time settings t_{Z3} =1.5s. If a measured impedance point is inside the Zone 3, then the delay time can be started and when the impedance stays longer than t_{Z3} , the logic decision generates the true value of the related output binary signal. It means that relay will trip with Zone 3 if the following conditions are met:

• Condition 1:

$$\begin{vmatrix} -\frac{R_3}{\cot{an22^0} + \cot{an68^0}} < X_{CAL} < X_3 \\ R_3 - \frac{R_3}{(\cot{an22^0} + \cot{an68^0}) \times \tan{68^0}} < R_{CAL} < R_3 + X_3\tan{68^0} \\ R_{CAL} < R_3 + X_{CAL}\tan{68^0} \end{vmatrix}$$

Condition 2:

$$\begin{cases} -\frac{R_{3}}{\cot an22^{\circ} + \cot an68^{\circ}} < X_{CAL} < X_{3} \\ 0 < R_{CAL} < R_{3} - \frac{R_{3}}{(\cot an22^{\circ} + \cot an68^{\circ}) \times tan68^{\circ}} \\ R_{CAL} > X_{CAL} tan22^{\circ} \end{cases}$$

Condition 3:

$$\begin{cases} 0 < X_{CAL} < X_{3} \\ -X_{CAL} tan 30^{0} < R_{CAL} < 0 \end{cases}$$



V. SIMULATION RESULTS

After the building of the proposed model has been completed, it is ready to analyze the secure operation of the quadrilateral characteristics of the three protection zones applied with variation in fault parameters like fault types, fault location from -5 km to 50 km, fault resistance from 1 Ω to 40 Ω . During a fault, the current in the faulted phases increases. The voltage in the faulted phases decreases beginning at 0.3 s. Distance protection zone outputs such as Z1, Z2, Z3, operate when the corresponding pre-set times are reached. After 10 ms the line is tripped and the voltage begins to recover. In case of an AG fault with $R_F=30 \Omega$ is created on the line Duy Xuyen-Thang Binh at a distance of 35 km from Duy Xuyen bus (forward direction). The distance represents 120.7% of the line length. Figure 10 shows the current and voltage waveform and a trip signal of protection zones before, during and after a fault. The fault occurs at 0.3 s, the current of phase A is increased and voltage of phase A is decreased. As a result, impedance trajectory seen by the relay entered into the characteristic second zone. Fault location displays 28.38 km. Relay takes 0.31 s to send trip signal Z2 to the circuit breaker.

Figure 11 shows the operation of relay in zone 1 with the presence of AB fault at distance 15 km with $R_F=10 \Omega$. The distance represents 51.7% of the line length. According to the change in voltage and current waveforms during the fault, the impedance trajectory moves quickly into Zone 1, fault location displays 14.29 km which results in a tripping at 0.322 s. In Figure 12, the result is shown where BCG fault is applied on the transmission line at distance 45 km with $R_F=40 \Omega$. According to the change in voltage and current waveforms during the fault, the apparent impedance seen at relay point is reduced but the trip signals are deactivated due to the movement of impedance trajectory out of Zone 3 area. Fault location displays 37.65 km. As shown in Figure 13, at 0.3 s an ABC fault occurs on the transmission line at 50 km. $R_F=1 \Omega$. and the fault duration is 1.5 s. According to the change in voltage and current waveforms during fault, relay impedance trajectory into Zone 3, fault location displays 49.47 km, thus trip signal Z3 is activated at 1.81 s. Some of the results for various fault cases (AG, BC, ABG, and ABC) are given in Table IV.



Fig. 10. Voltage, current waves, trip sinals and impedance trajectory for faults at AG fault with R_F =30 Ω at 35km from relay point



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Fig. 11. Voltage, current waves, trip sinals and and impedance trajectory for AB fault with R_F =10 Ω at 15km from relay point





The power system is supplied from both ends, its setting for Zone 1 is 85 percent of line length or 24.65 km. Similarly, Zone 2 is 35.18 km, and Zone 3 is 57.9 km. In the tests, the fault resistance influence on the measured distance to fault location, the highest fault resistance that allowed for reliable distance protection relay is 20 Ω . In the case of the high

resistance fault, this value changes from 20 to 25 Ω , the final point of fault impedance locus falls under Zone 1 characteristic or under-reaching tendency. If it is higher than 40 Ω , fault impedance locus out of zone protection with corresponding error increases.

Phase	Actual fault	Fault	Measured fault	Zone
	location (km)	resistance (Ω)	location (km)	trip
	-5	10	-12.2	/
	5	1	4.718	Z1
	10	5	9.244	Z1
	15	10	13.7	Z1
AG	20	15	18.21	Z1
	25	20	22.78	Z1
	30	25	24.75	Z1
	35	30	31.42	Z2
	40	35	35.25	Z2
	45	40	38.35	/
	50	1	49.67	Z3
	-5	10	-9.475	/
	5	1	4.923	Z1
	10	5	9.633	Z1
	15	10	14.29	Z1
	20	15	18.96	Z1
AB	25	20	23.63	Z1
	30	25	28.15	Z1
	35	30	31.92	Z2
	40	35	35.31	Z2
	45	40	37.65	/
	50	1	49.47	Z3
	-5	10	-9.455	/
	5	1	4.919	Z1
	10	5	9.919	Z1
	15	10	14.92	Z1
	20	15	19.93	Z1
BCG	25	20	23.62	Z1
	30	25	28.14	Z1
	35	30	31.91	Z2
	40	35	35.31	Z2
	45	40	37.65	/
	50	1	49.47	Z3
	-5	10	-9.48	/
	5	1	4.919	Z1
	10	5	9.633	Z1
	15	10	14.29	Z1
ABC	20	15	18.95	Z1
	25	20	23.62	Z1
	30	25	28.15	Z1
	35	30	31.92	Z2
	40	35	35.31	Z2
	45	40	37.65	/
	50	1	49.47	Z3

TABLE IV. TEST RESULTS

VI. CONCLUSIONS

In this study, the distance protection function with three forward zones has been implemented in a Siemens 7SA522 distance protection relay on the 110kV Duy Xuyen–Thang Binh transmission line that was simulated easily and reliably in Matlab Simulink. The proposed model allows us to include the detailed analysis of the impedance (R_{CAL} , X_{CAL}) measured by the distance relay on one single end, fault detection, fault classification, and tripping protection zones for fault, considering fault location, fault type existing on the

transmission line, and fault resistance. According to the obtained results, it has been shown that the accuracy of the relay depends on a fault resistance value. The high fault resistance causes the distance relay to over-reach or under-reach. Therefore, a correctly set distance protection relay can correctly compute the fault location, mitigate the problem of mal-operation, thus ensuring effective and reliable protection to the transmission line.



Fig. 13. Voltage, current waves, trip sinals and impedance trajectory for faults at ABC fault with $RF = 1\Omega$ at 50km from relay point

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